



SPACEPORT

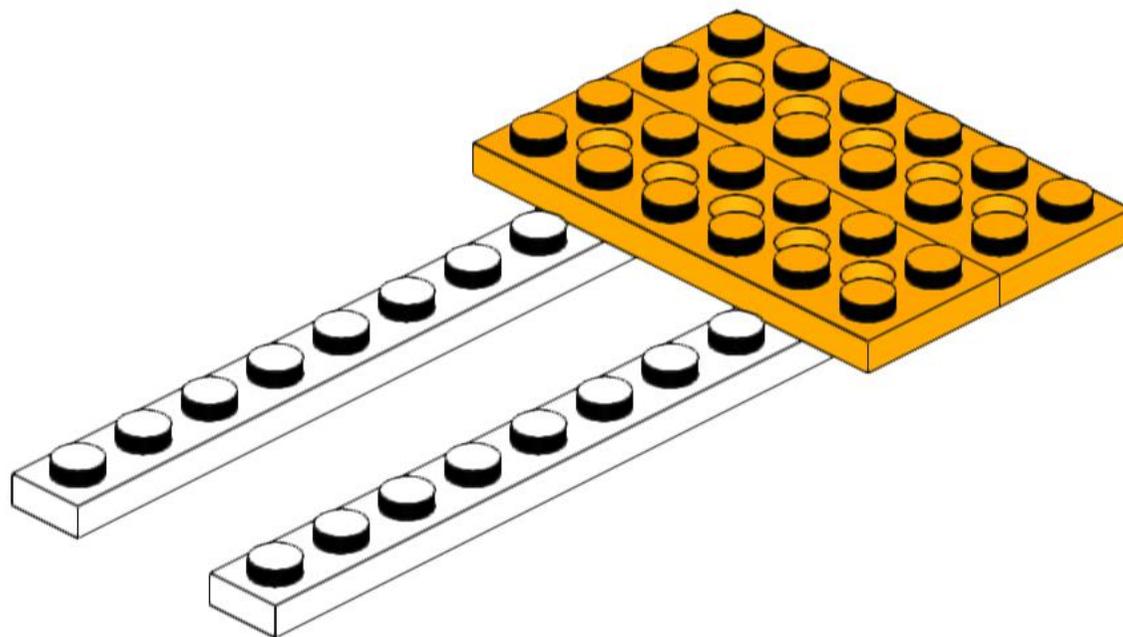
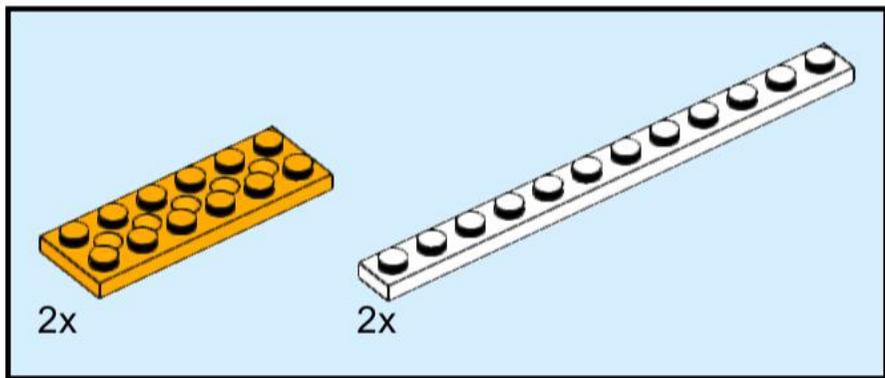
Building instruction
for kit Lego Wedo 2.0



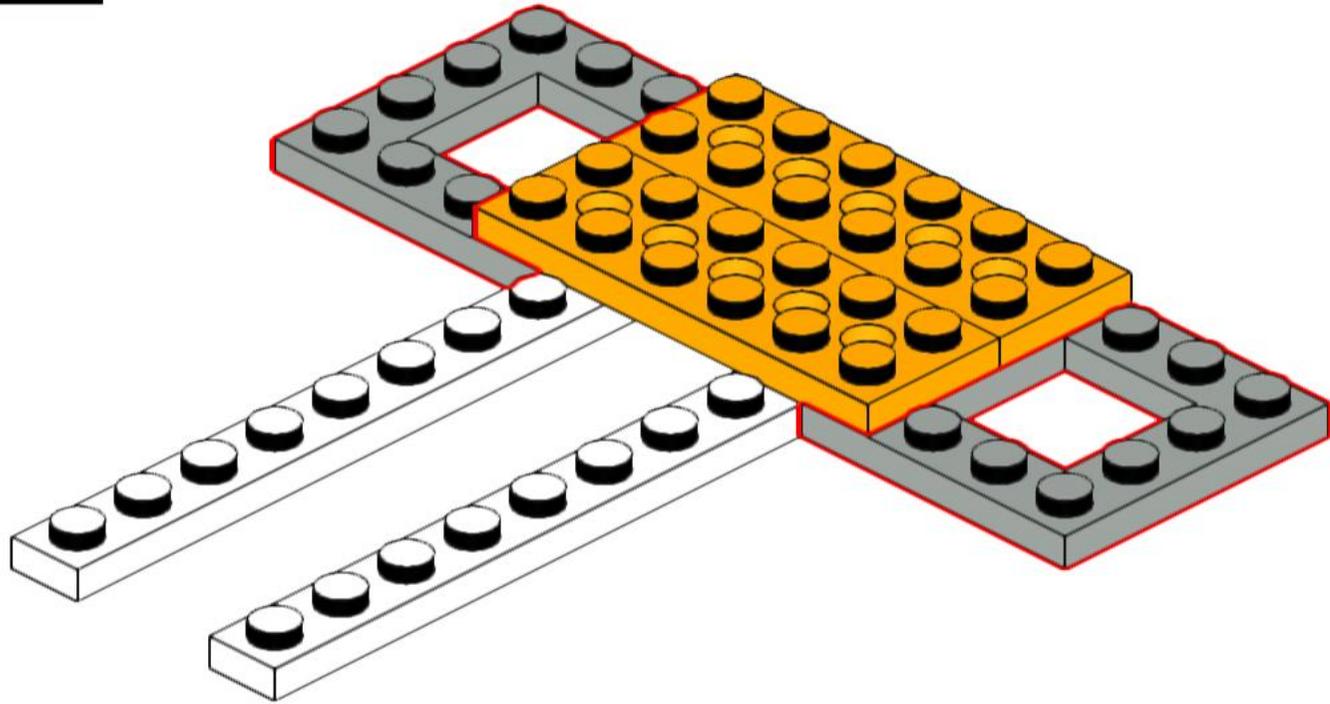
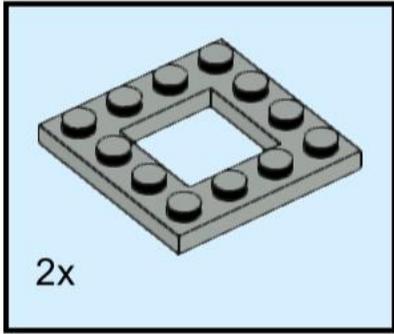
roboinstruction.com



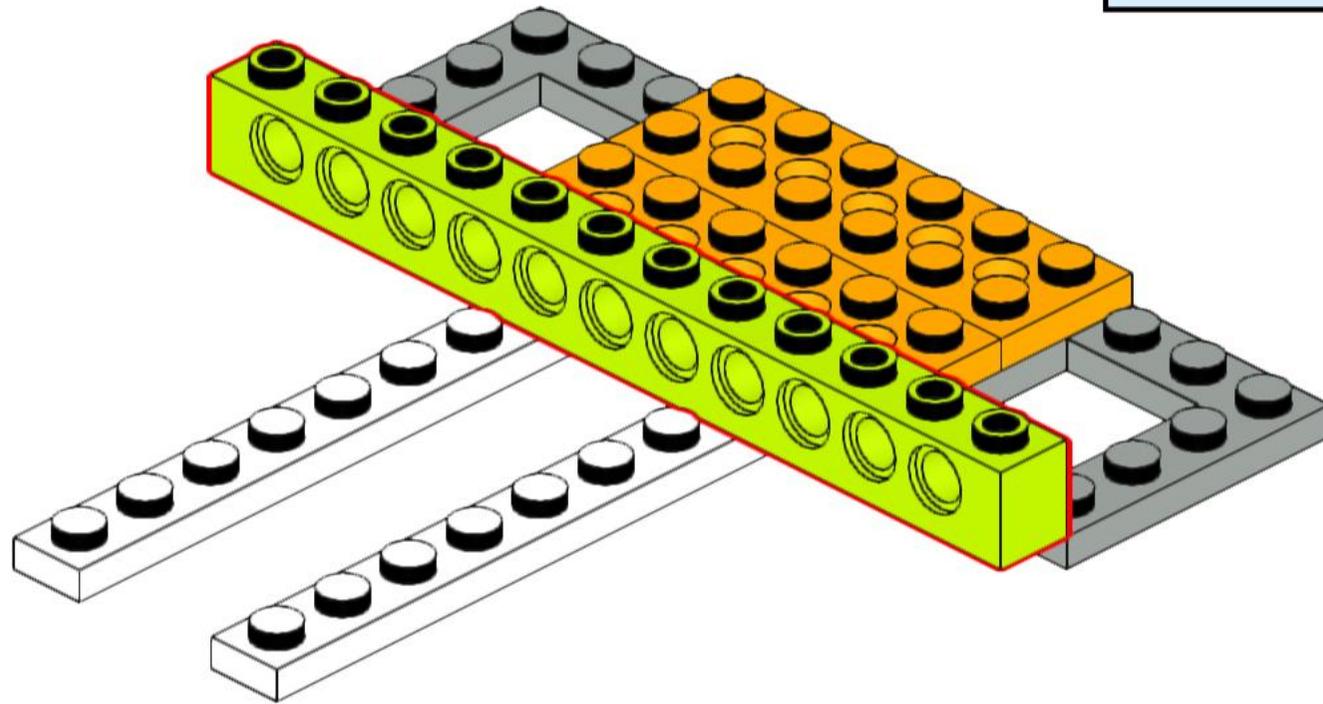
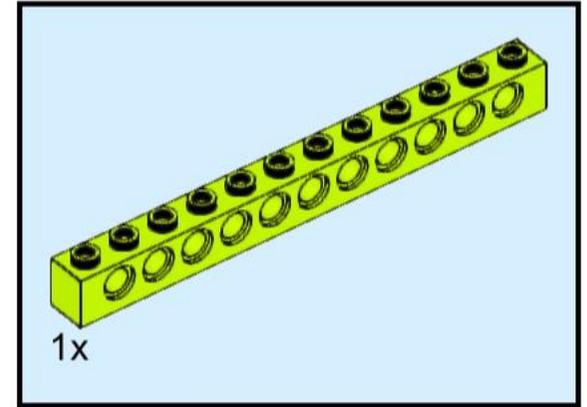
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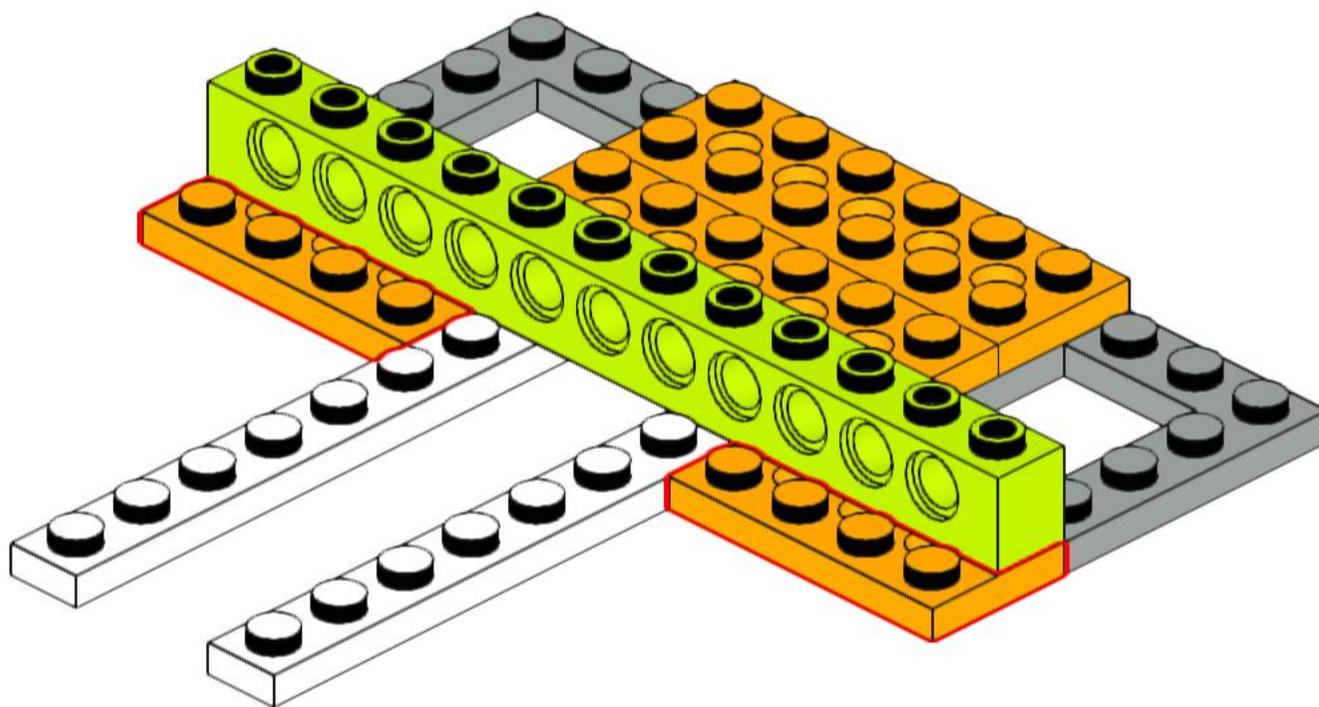
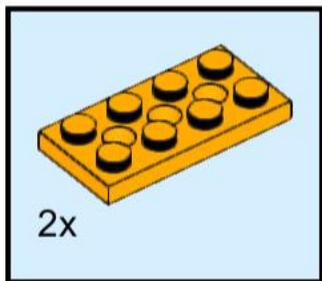
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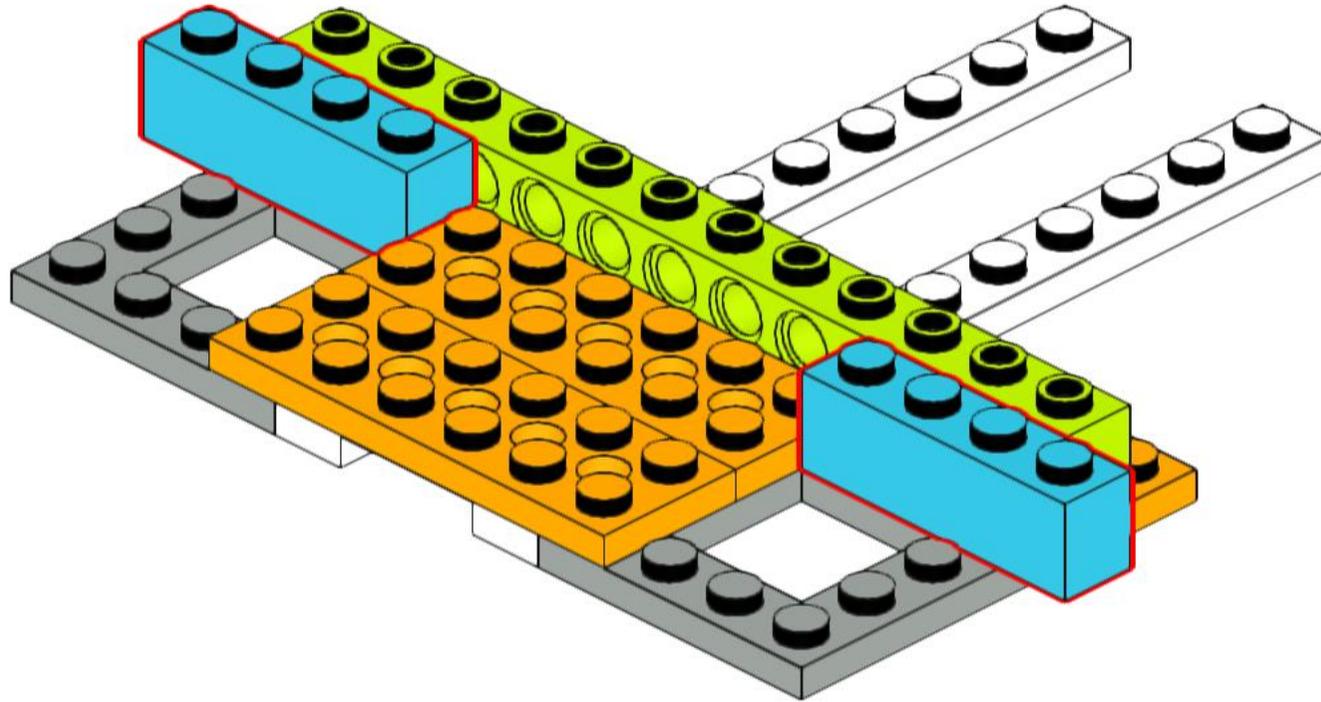
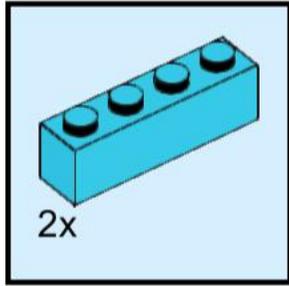
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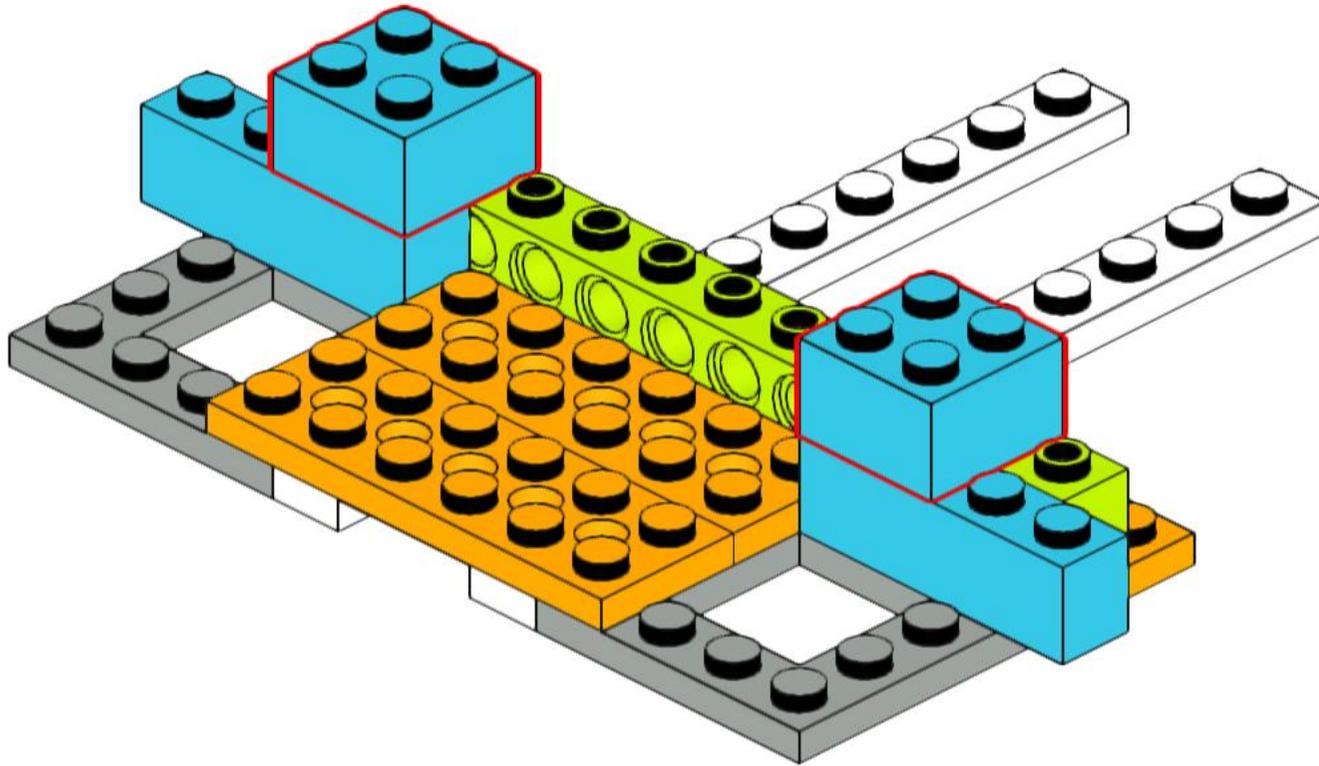
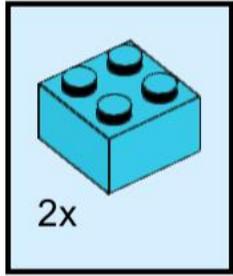
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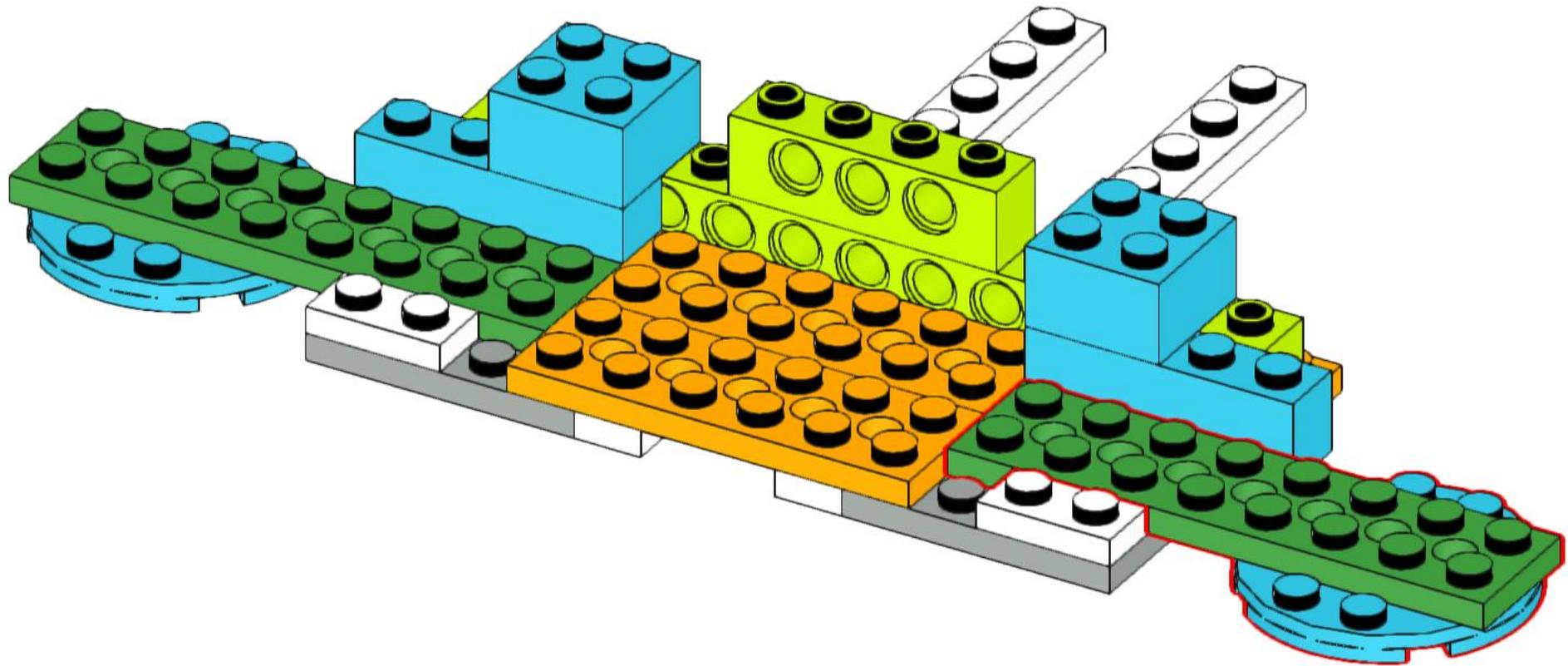
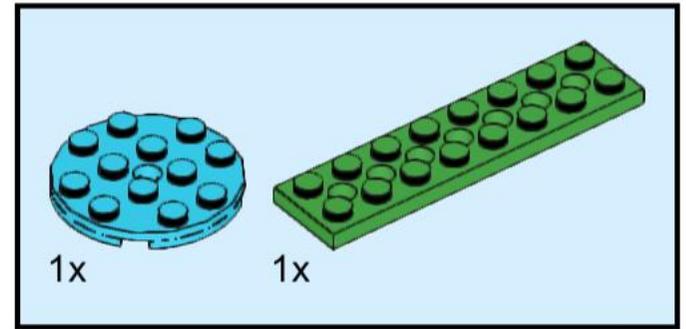
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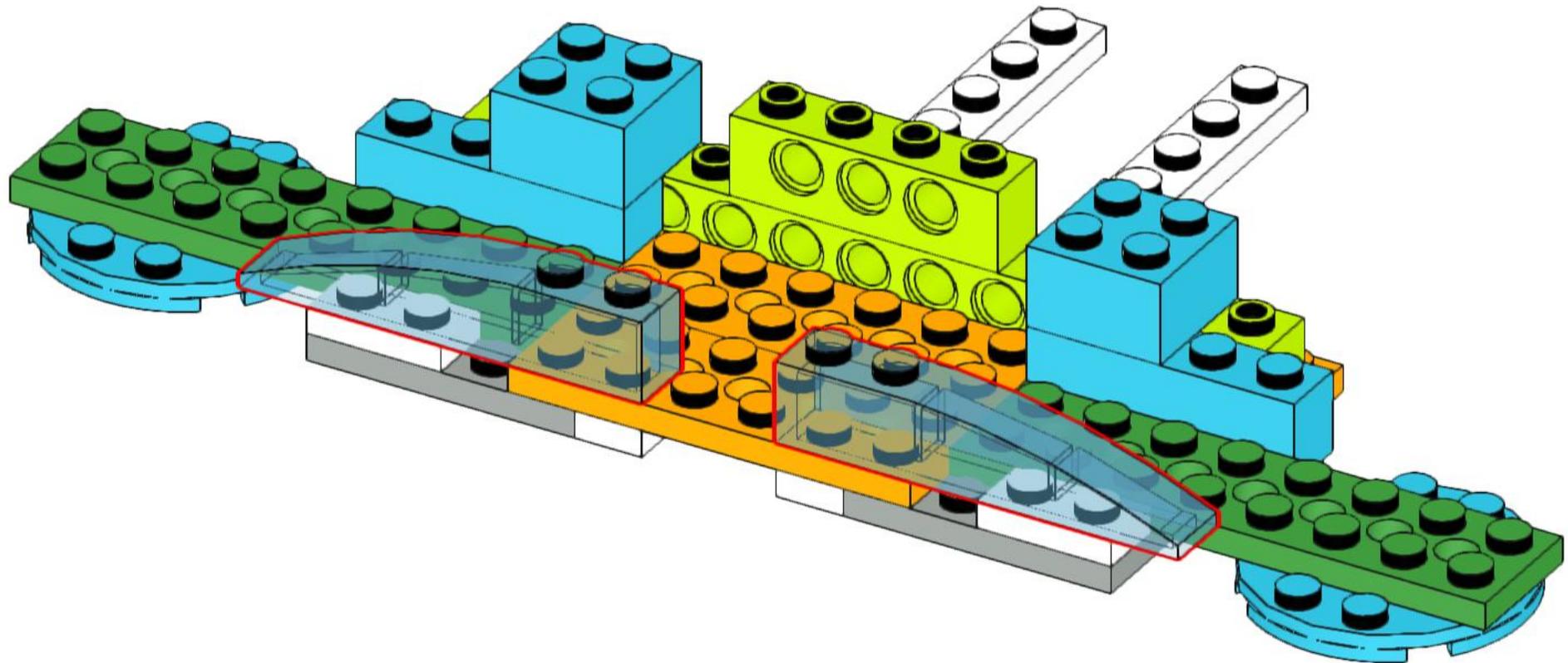
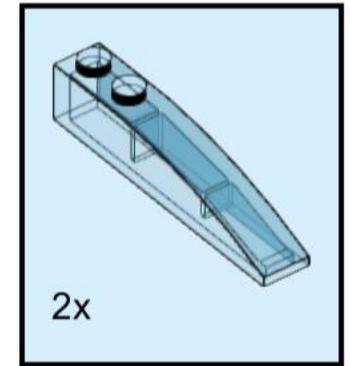
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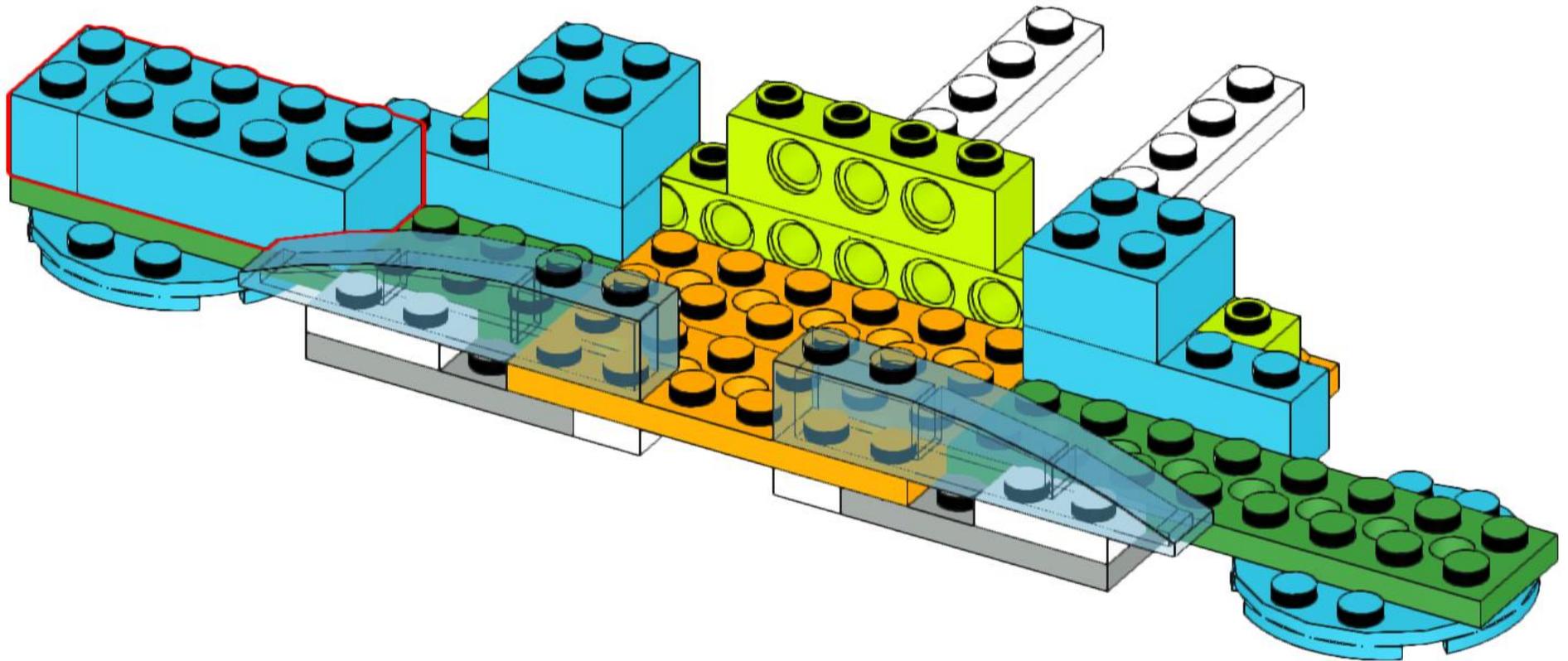
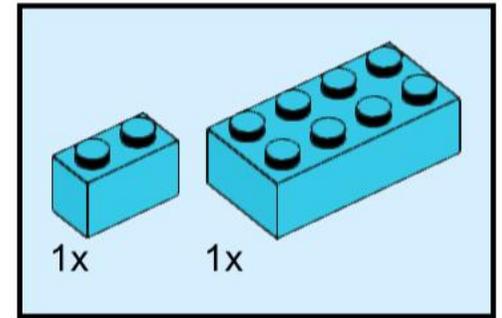
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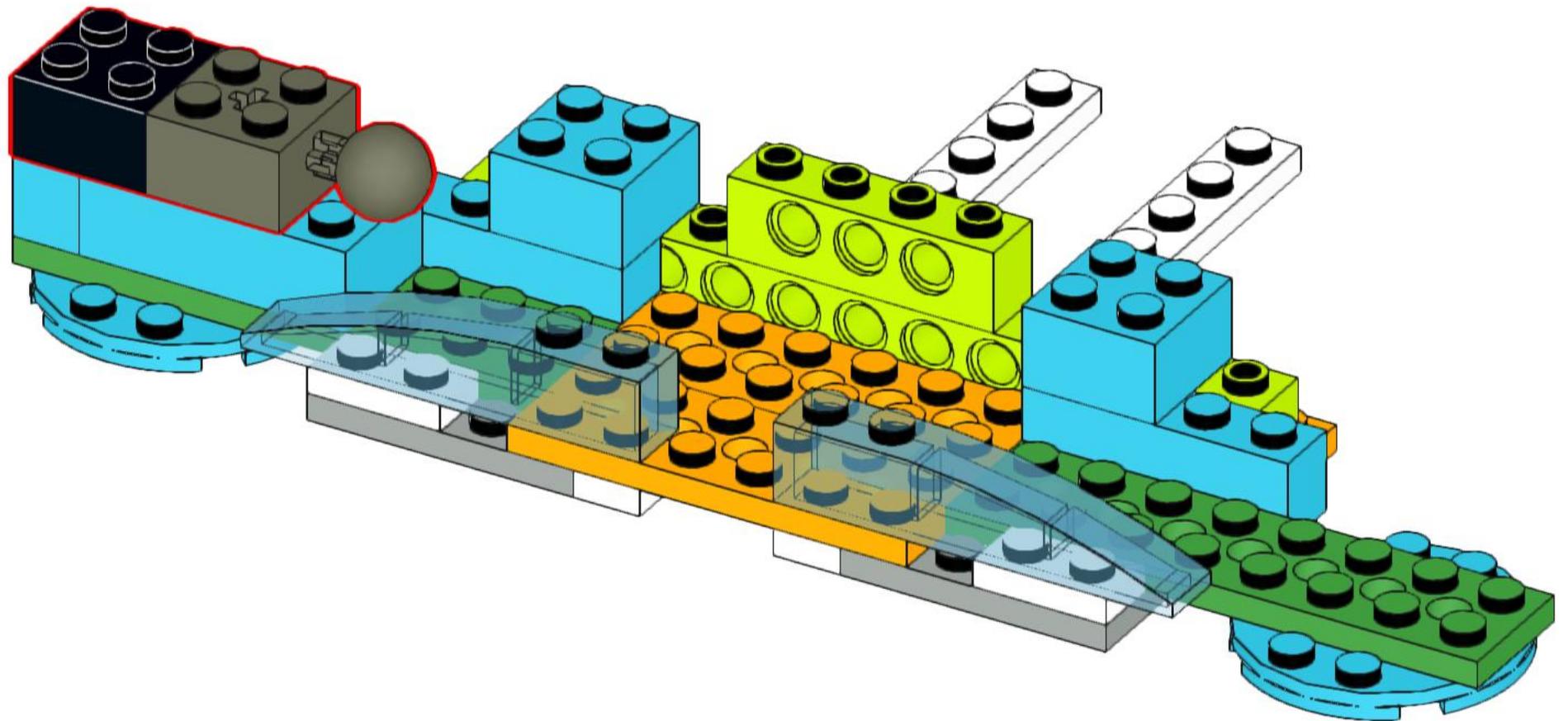
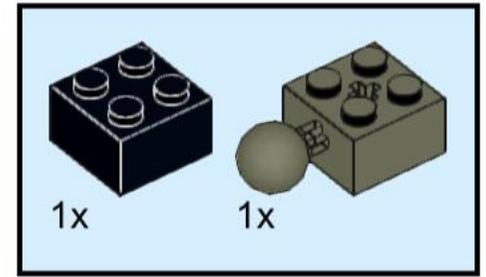
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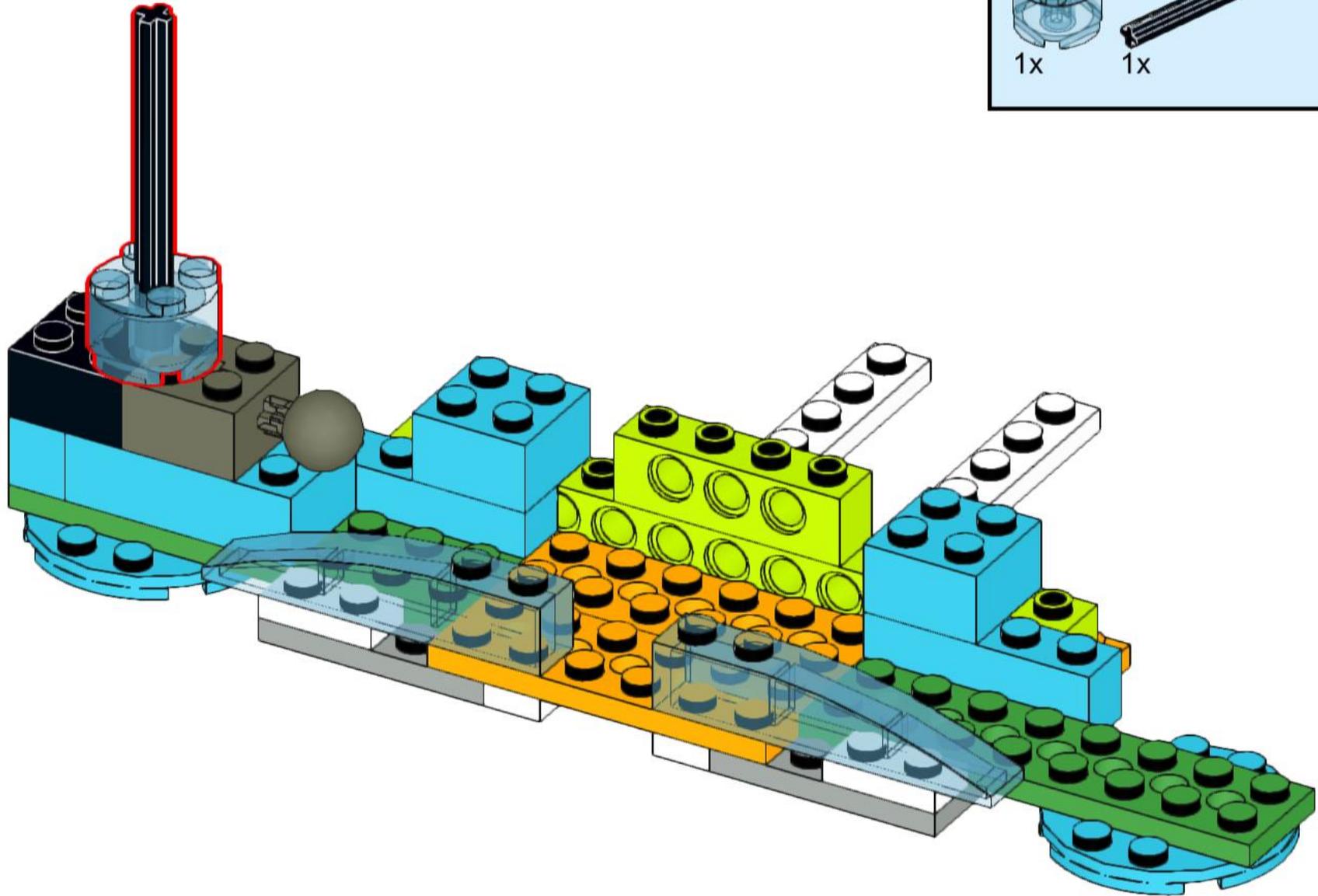
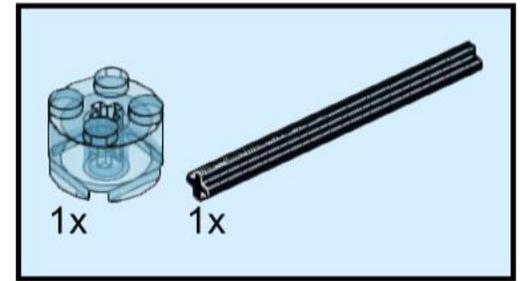


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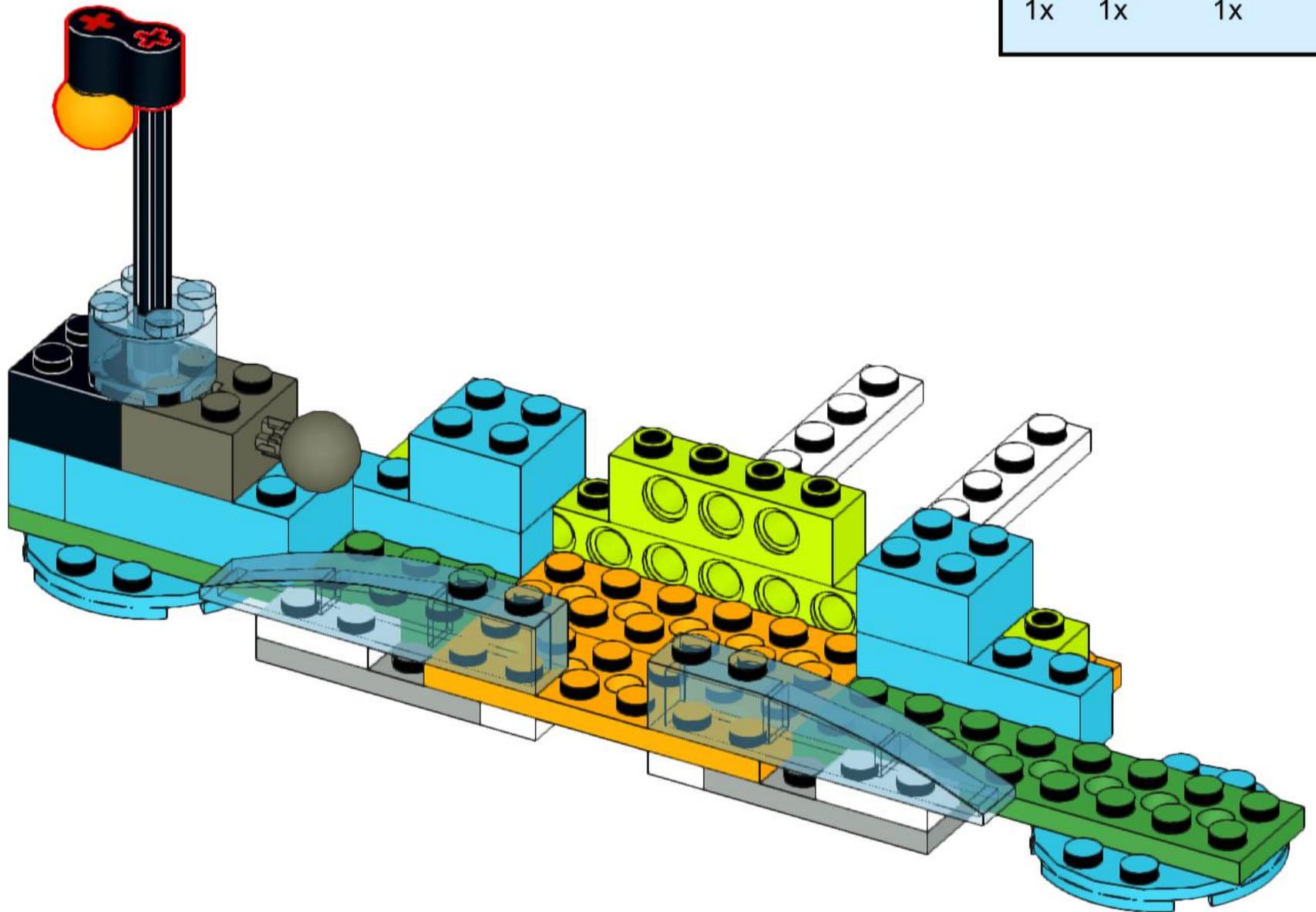
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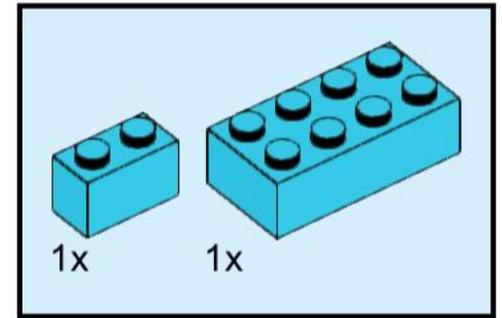
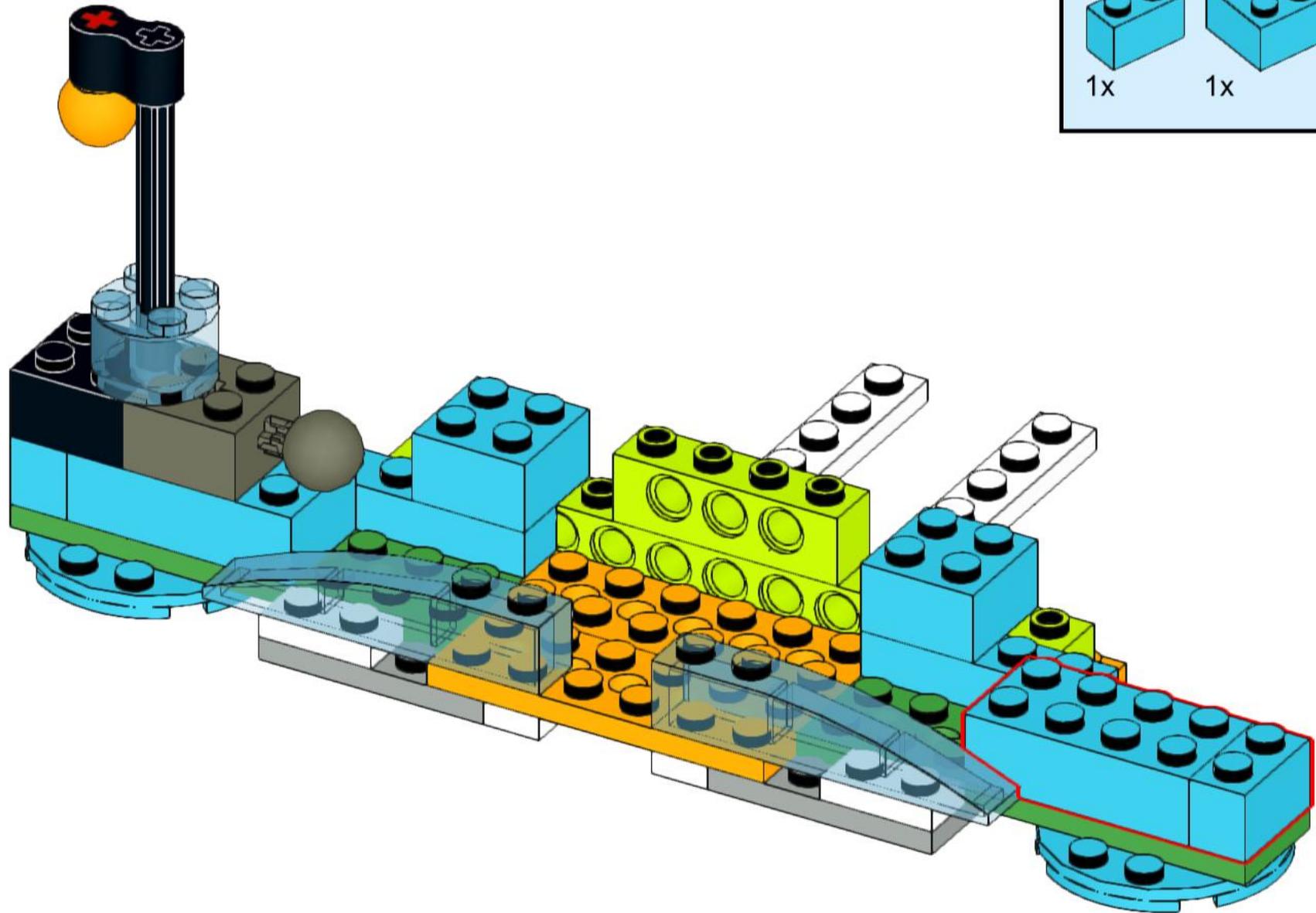
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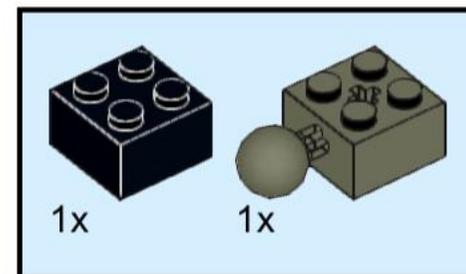
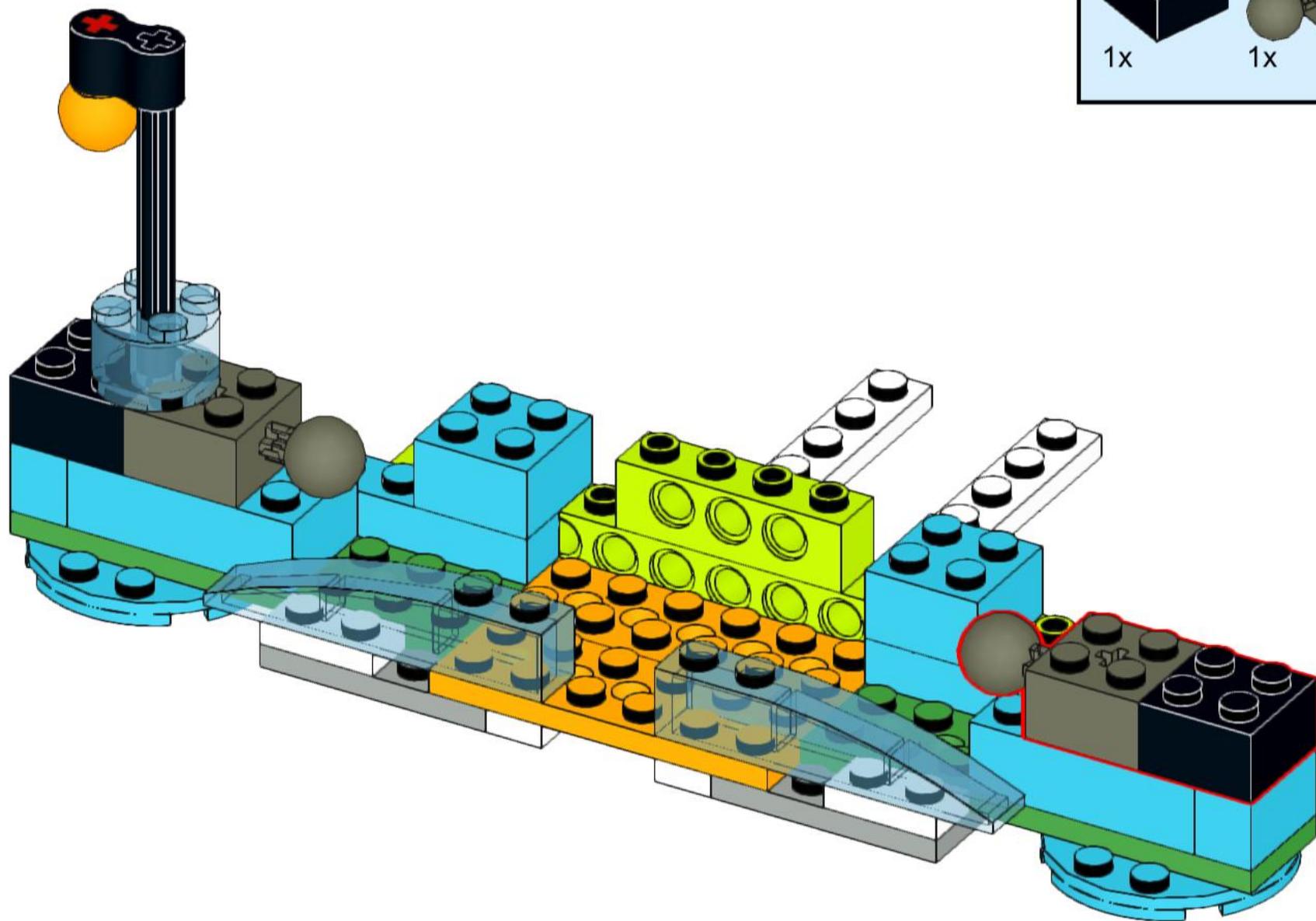
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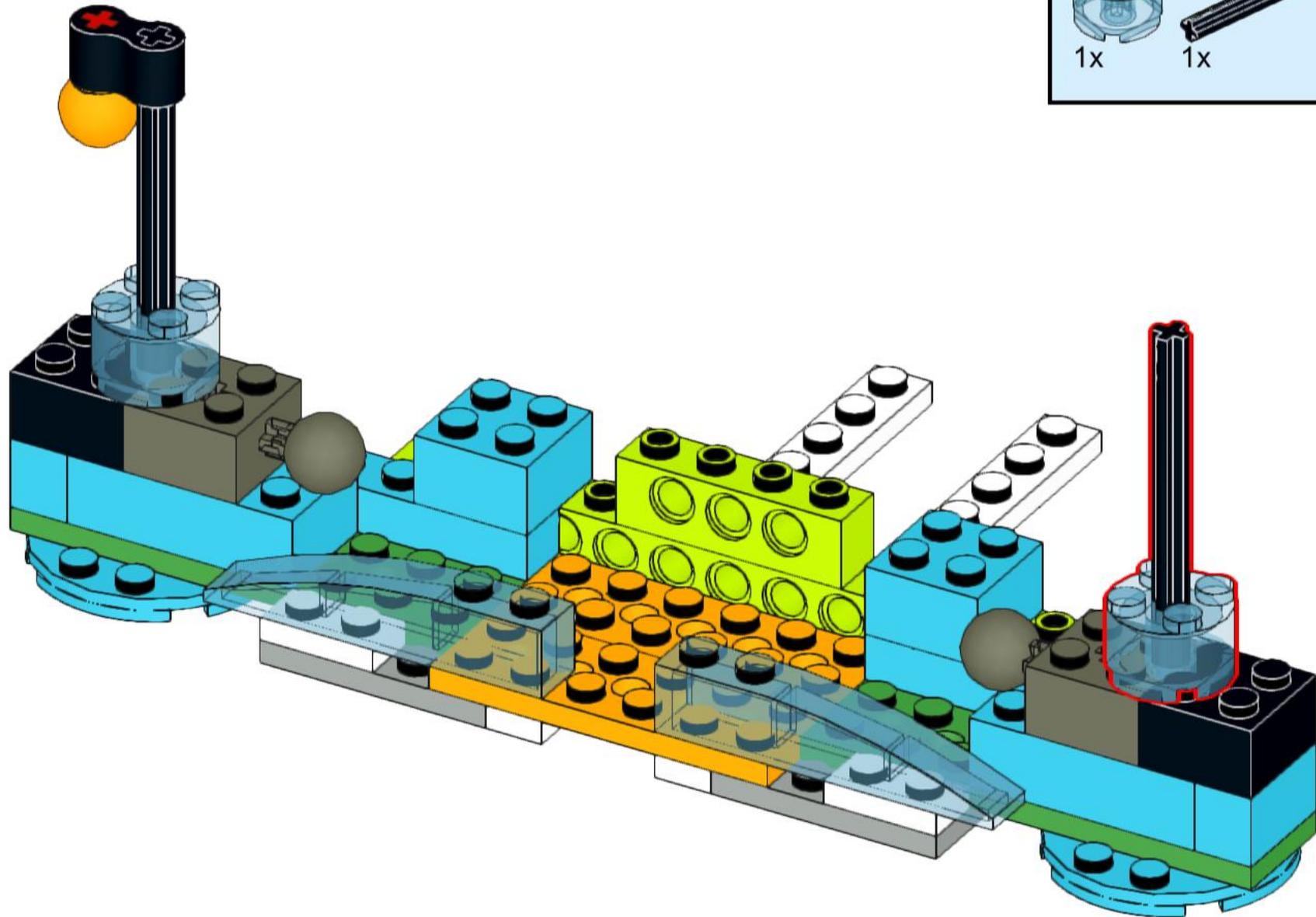
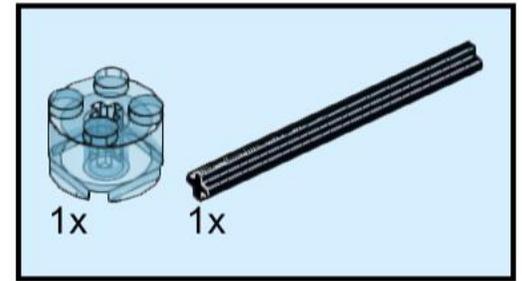
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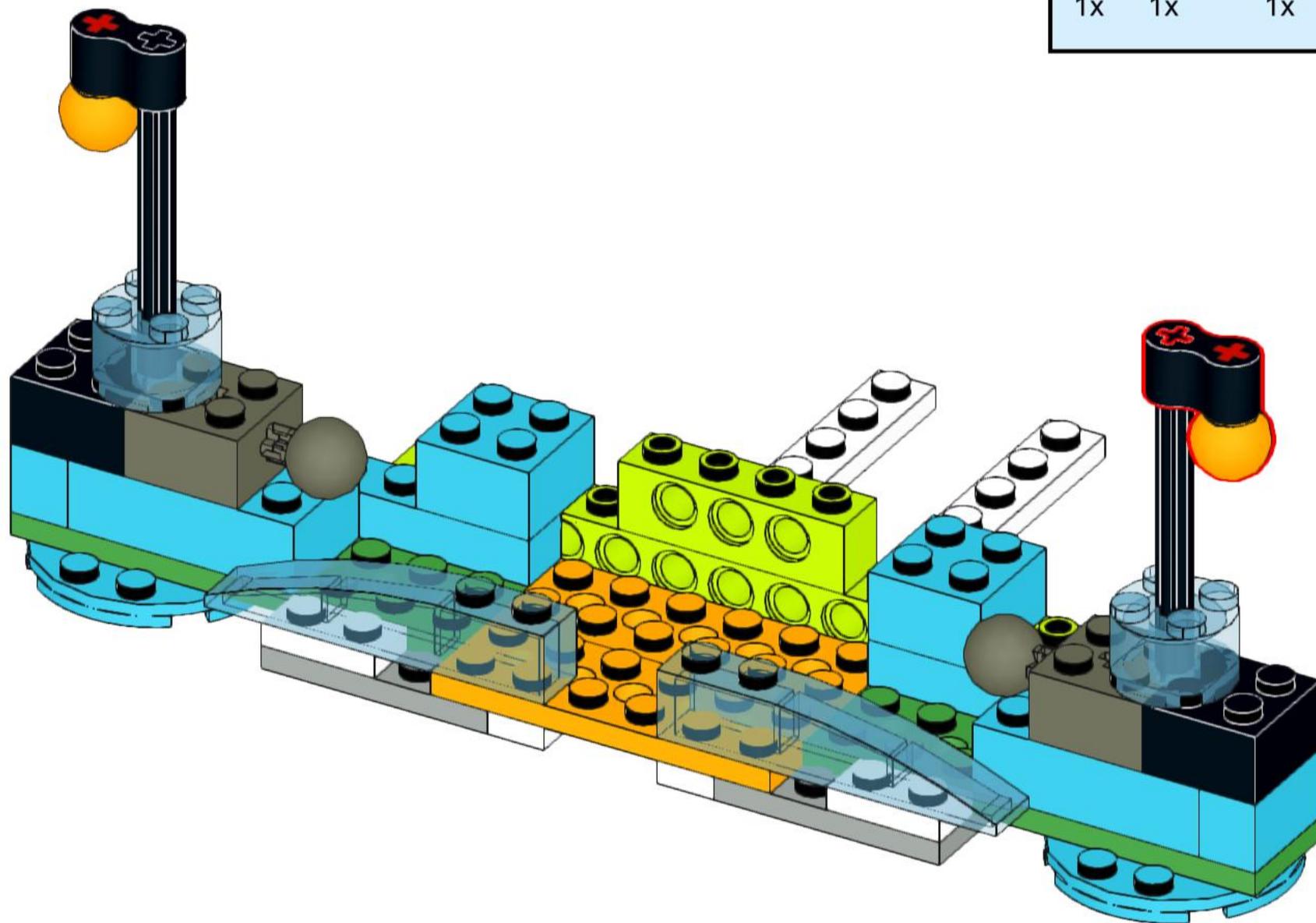
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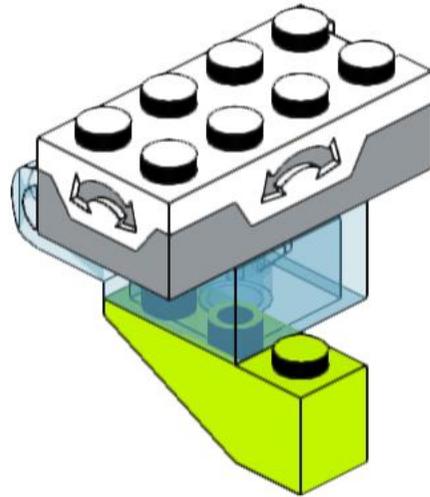
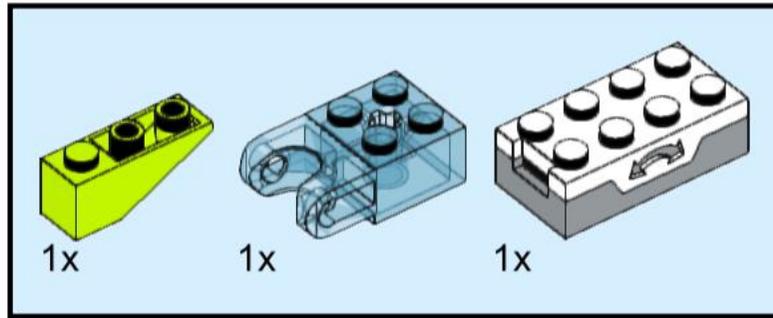
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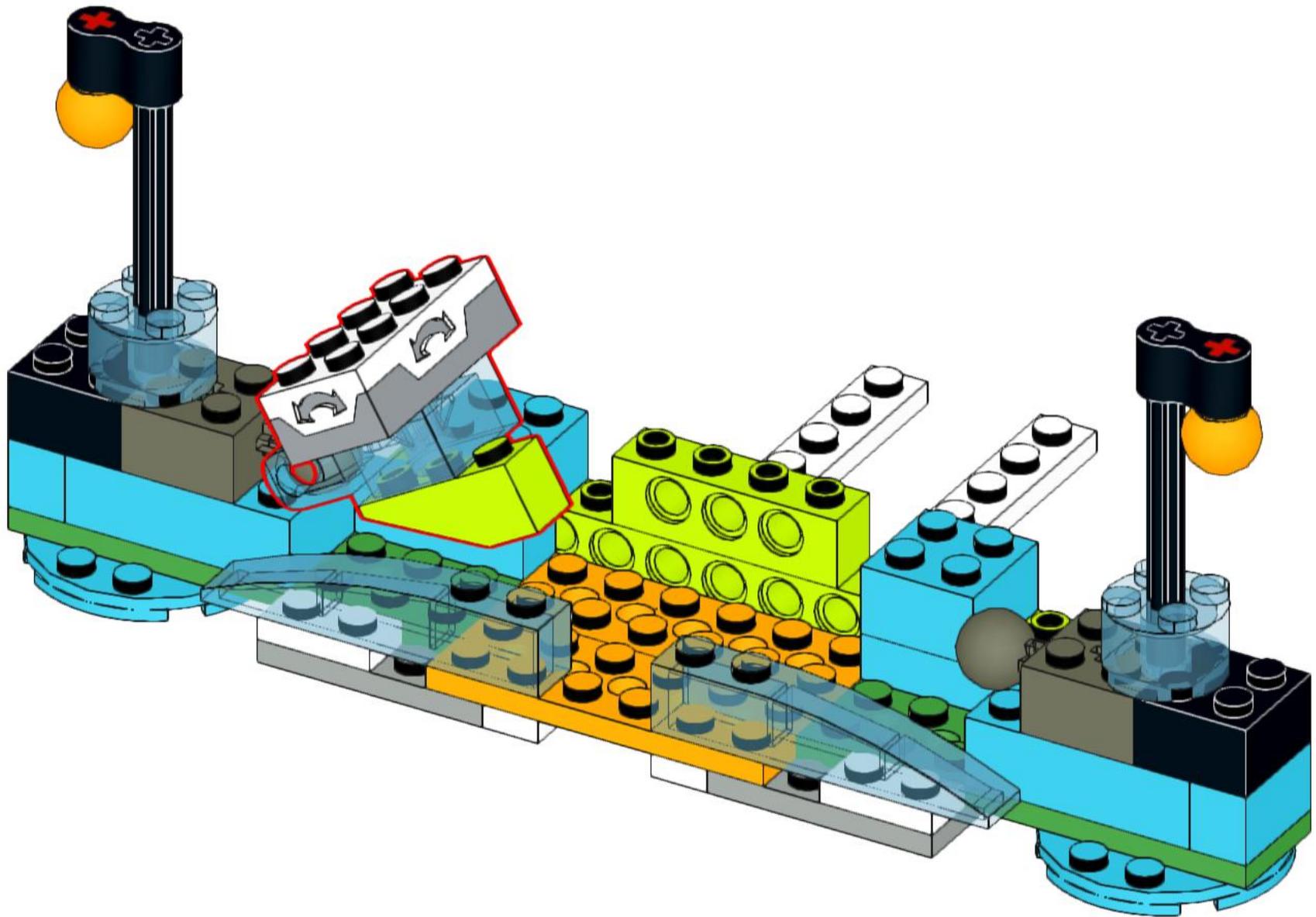
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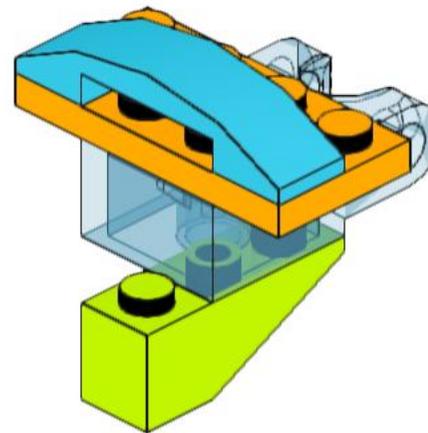
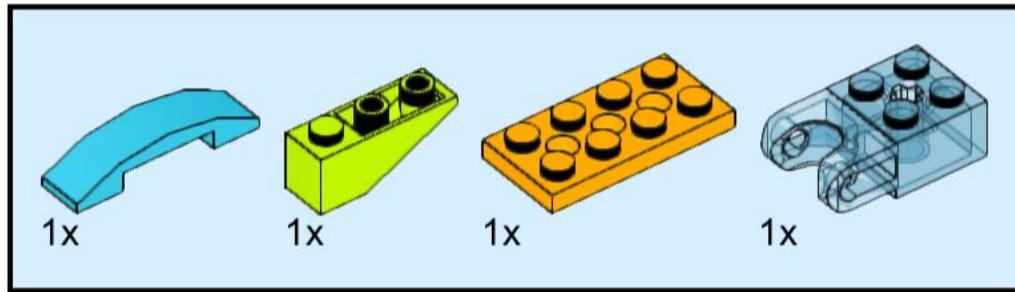
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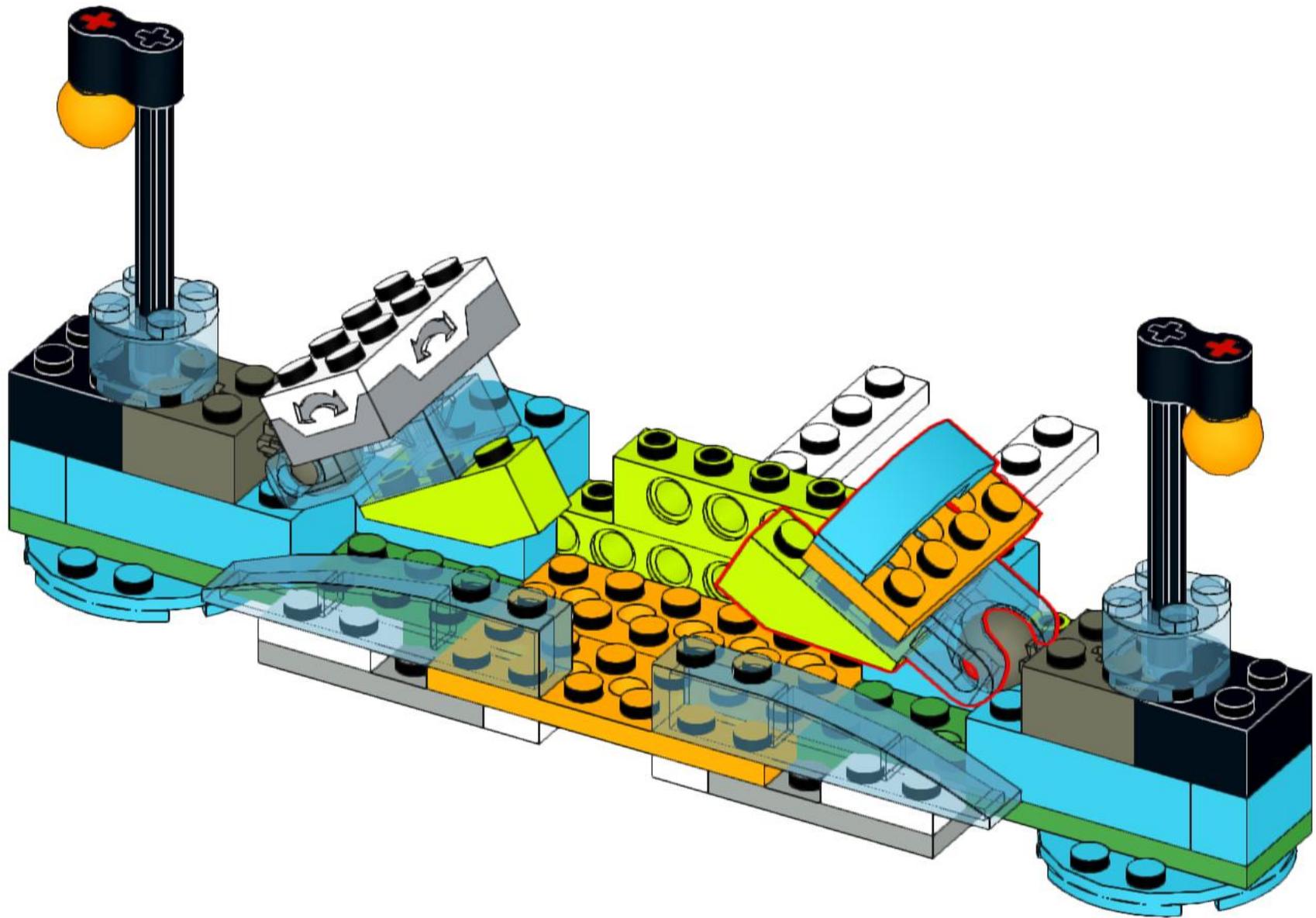
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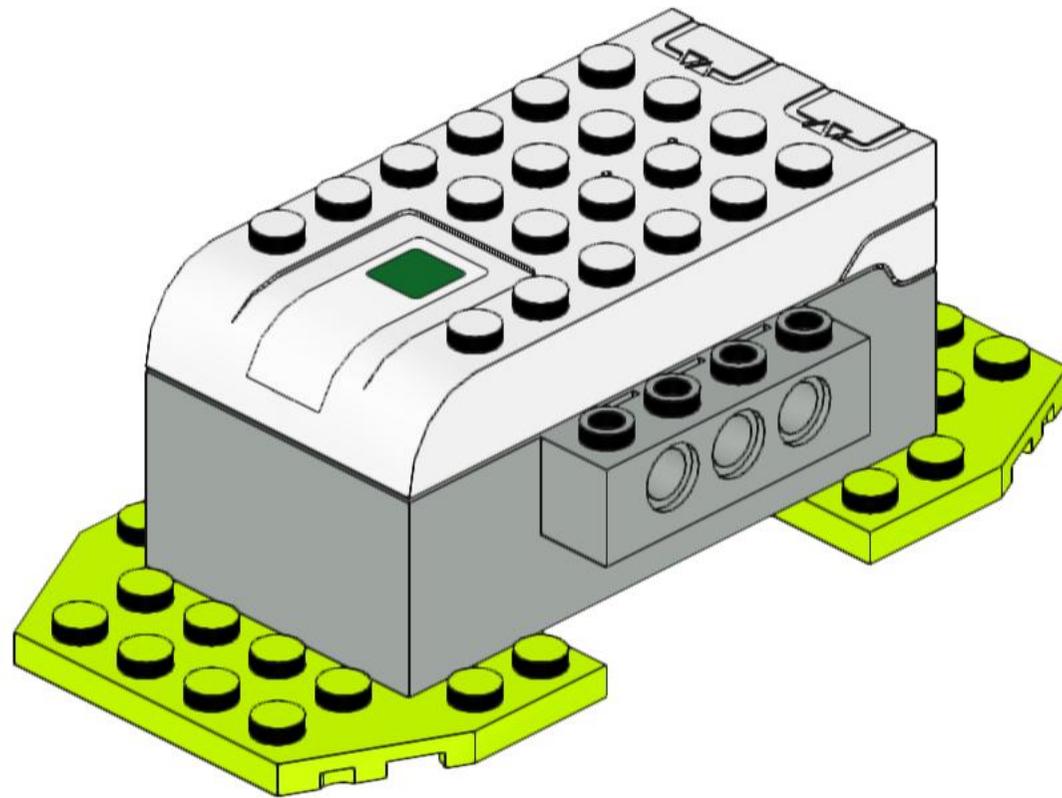
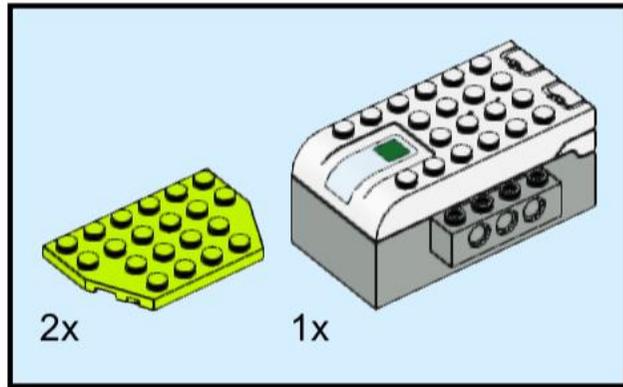
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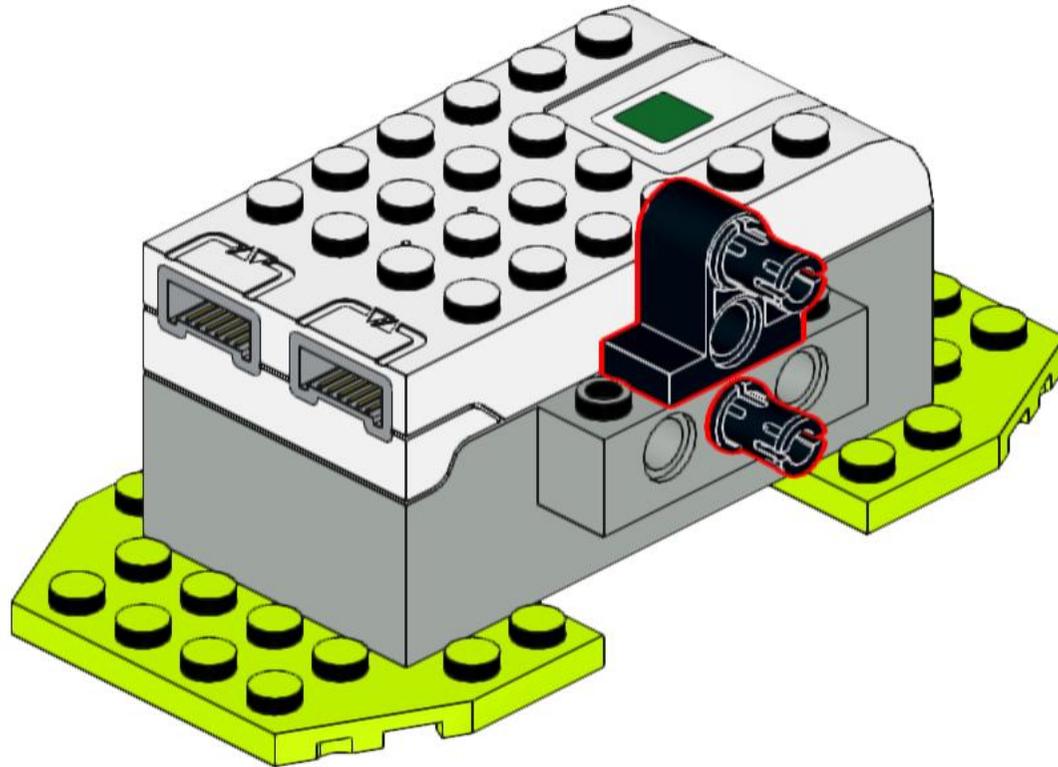
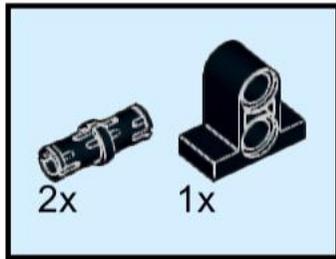
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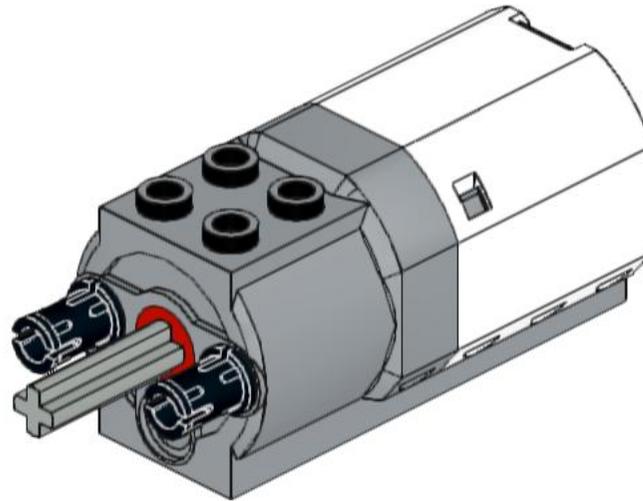
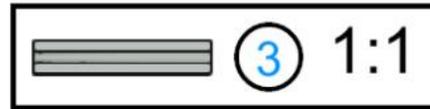
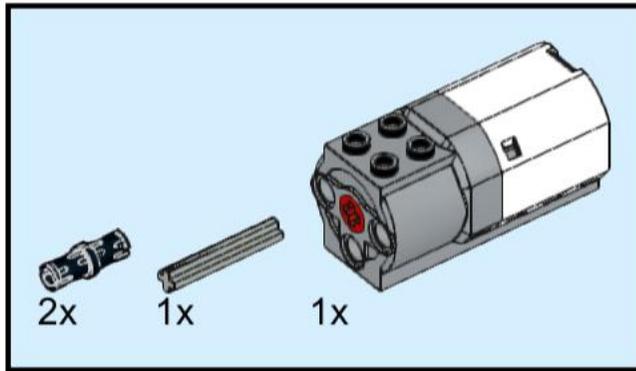
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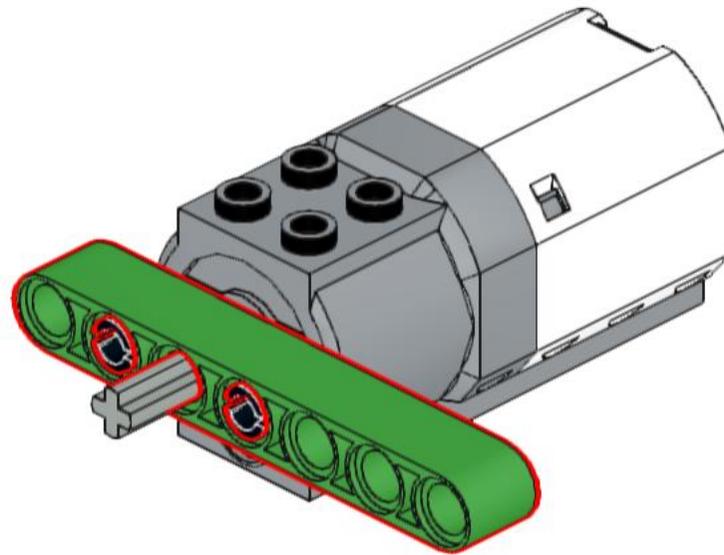
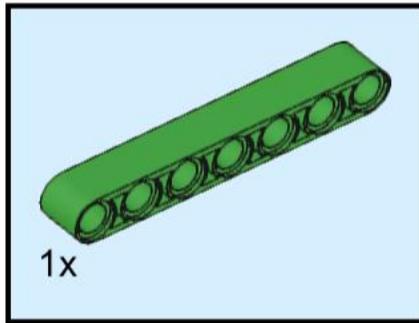
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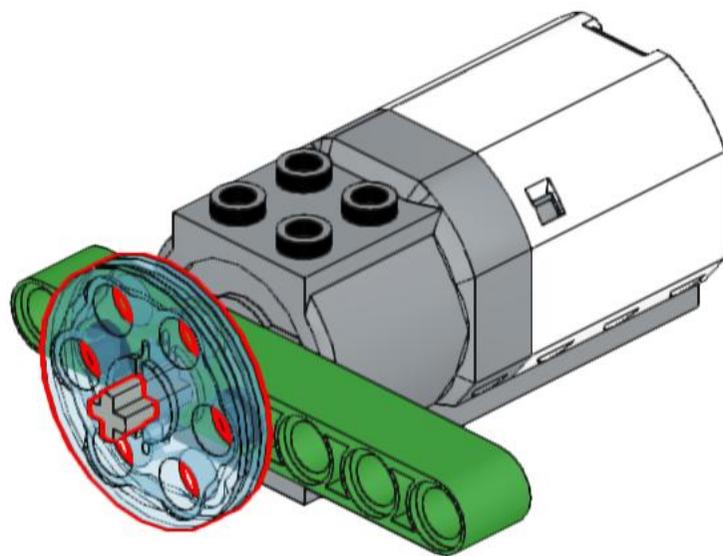
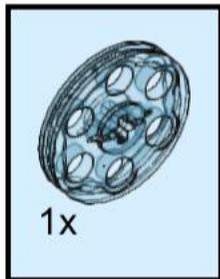
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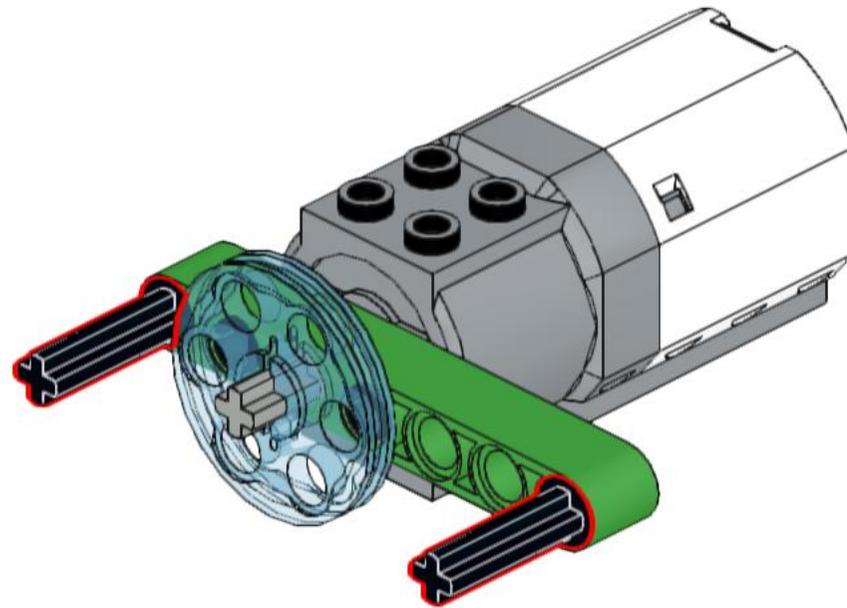
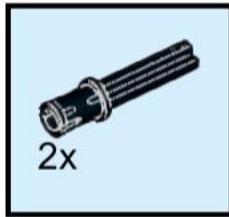
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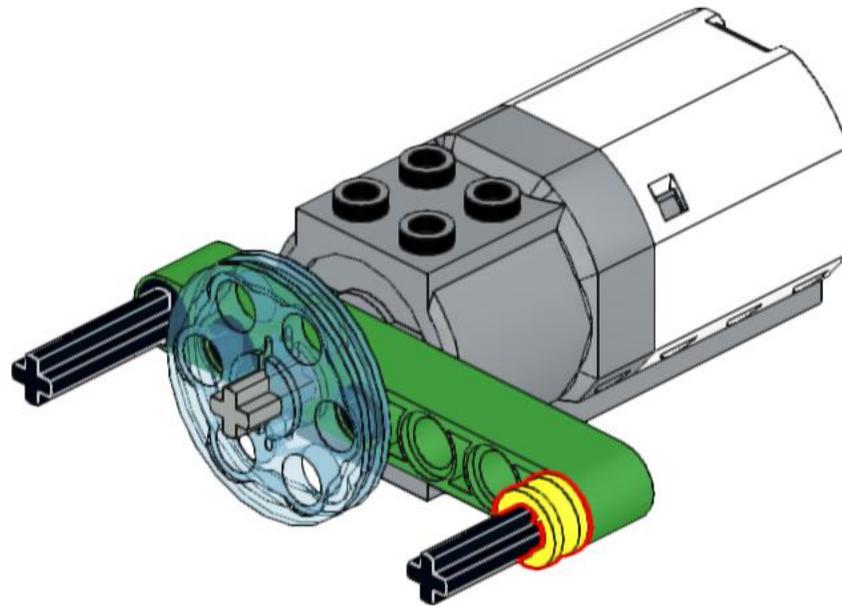
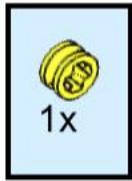
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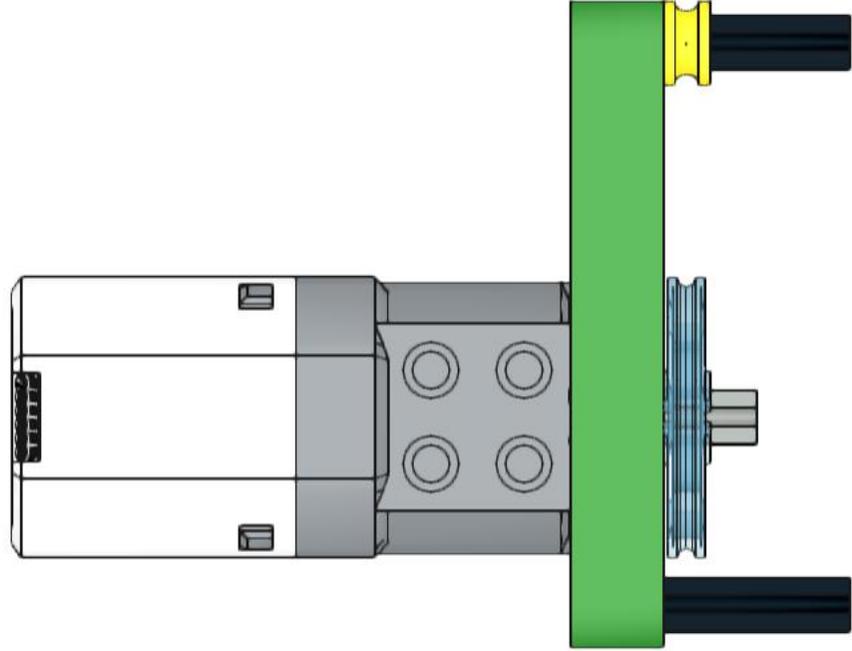
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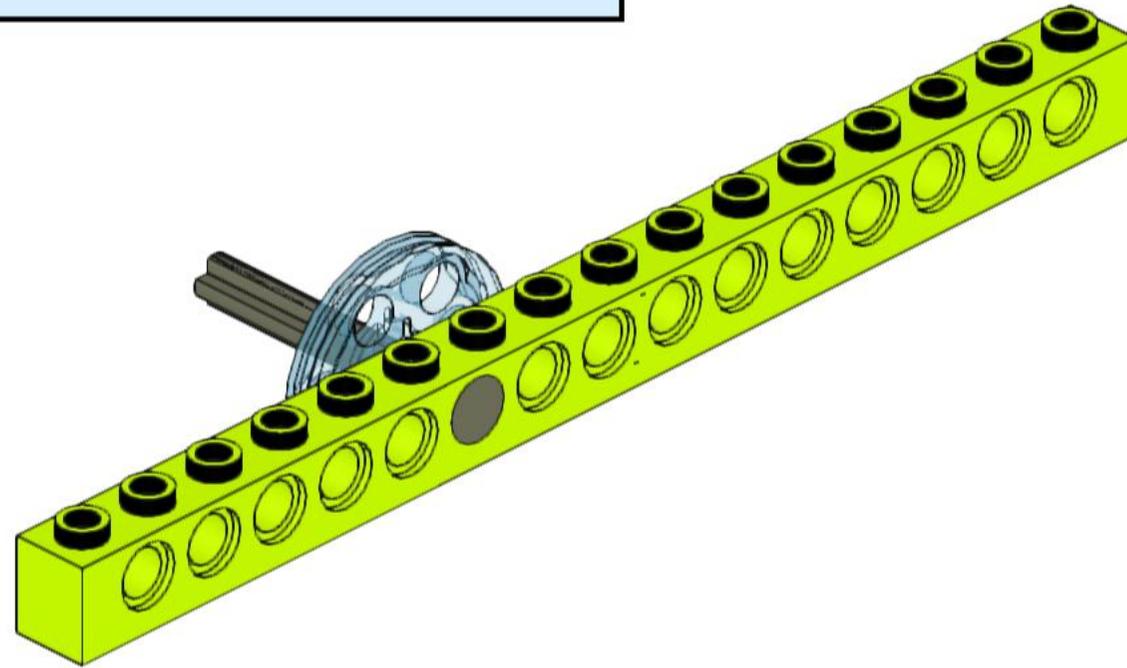
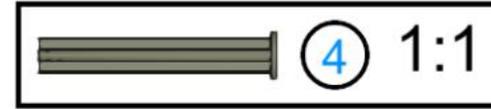
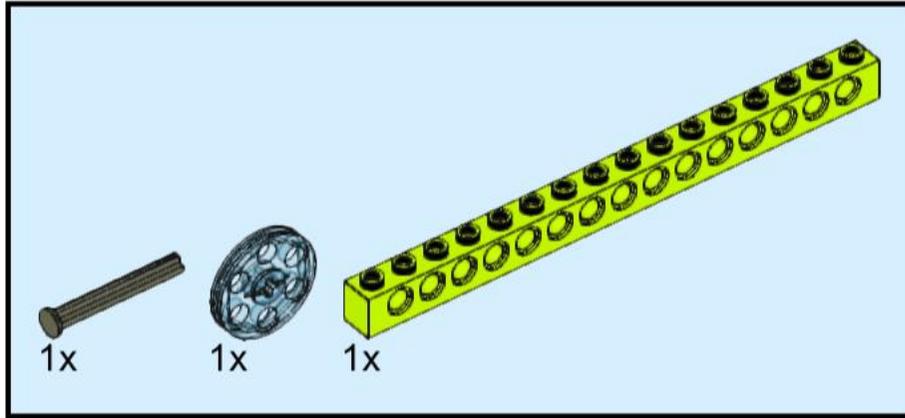
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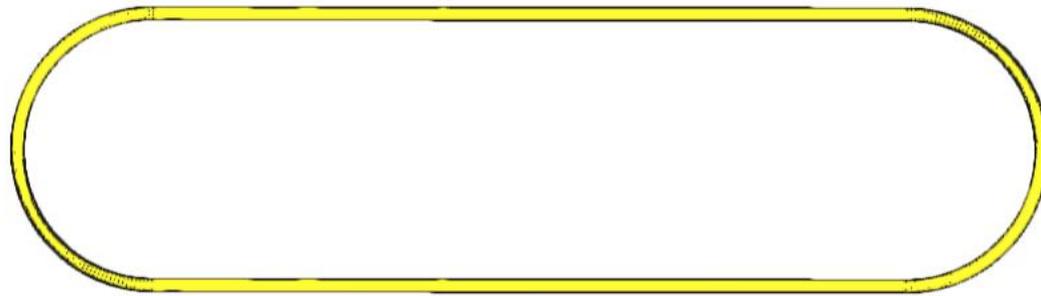


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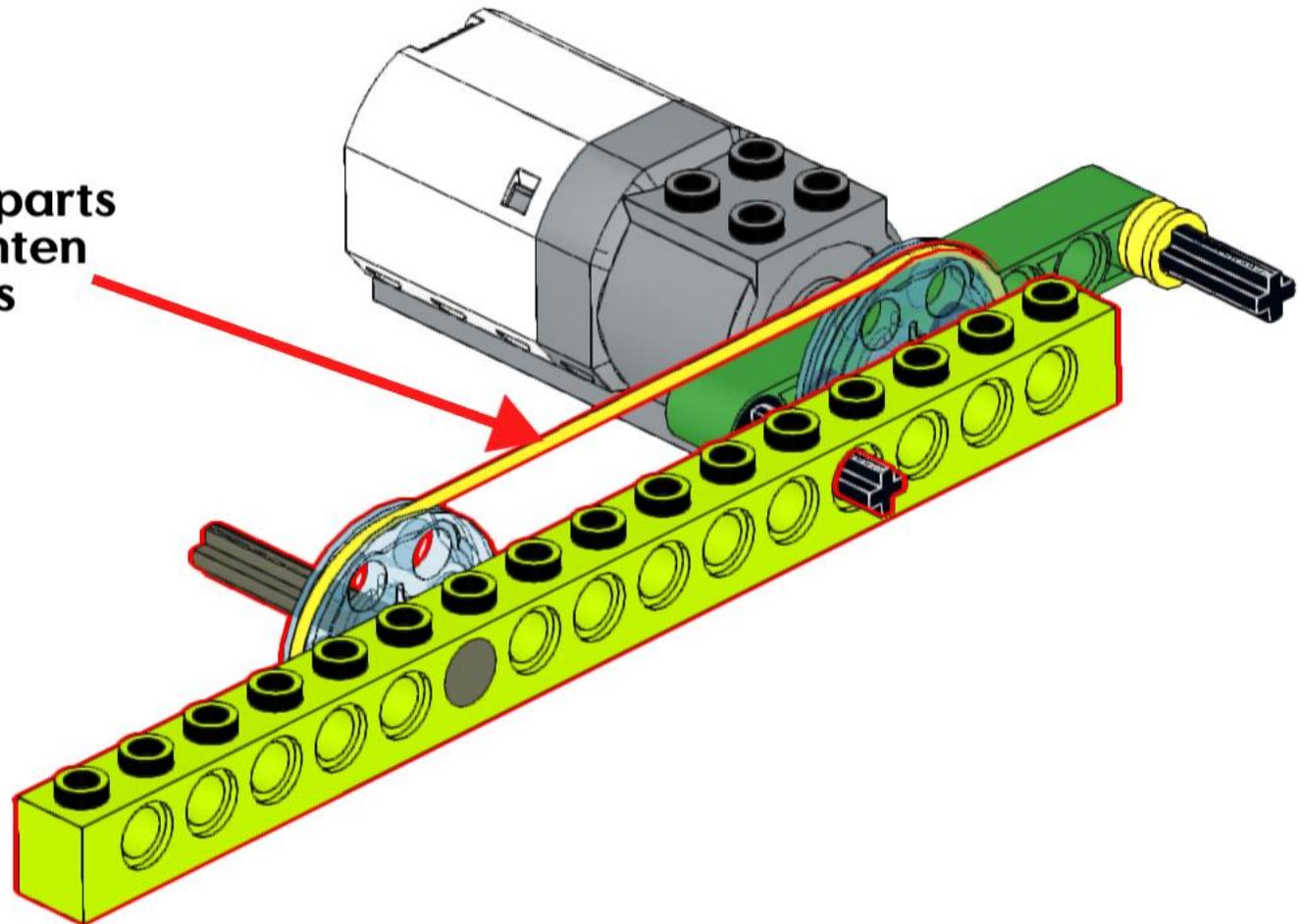
FIND THE RUBBER BELT!



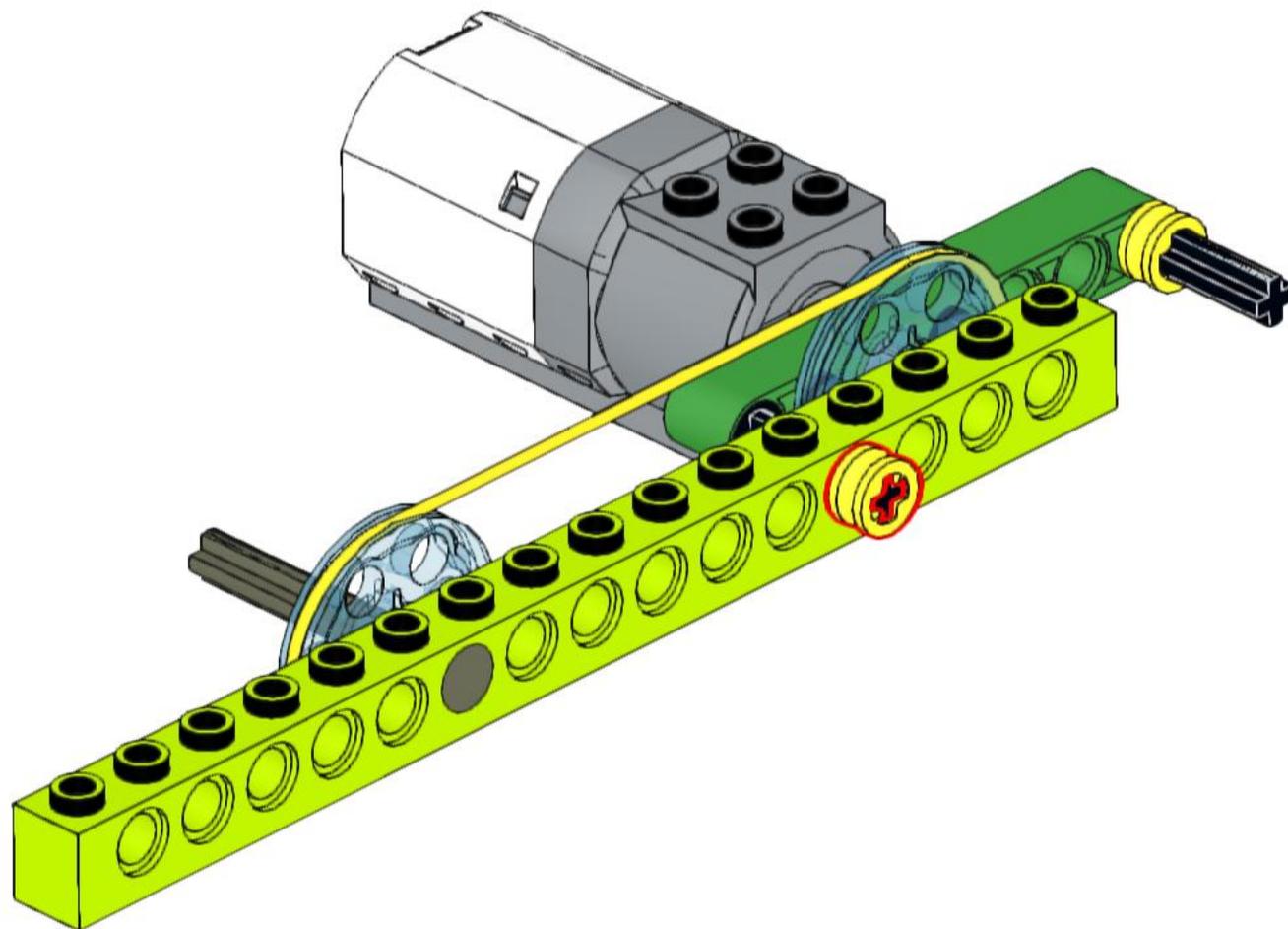
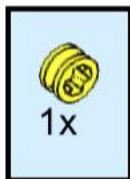
Guess, where the right place of setting?

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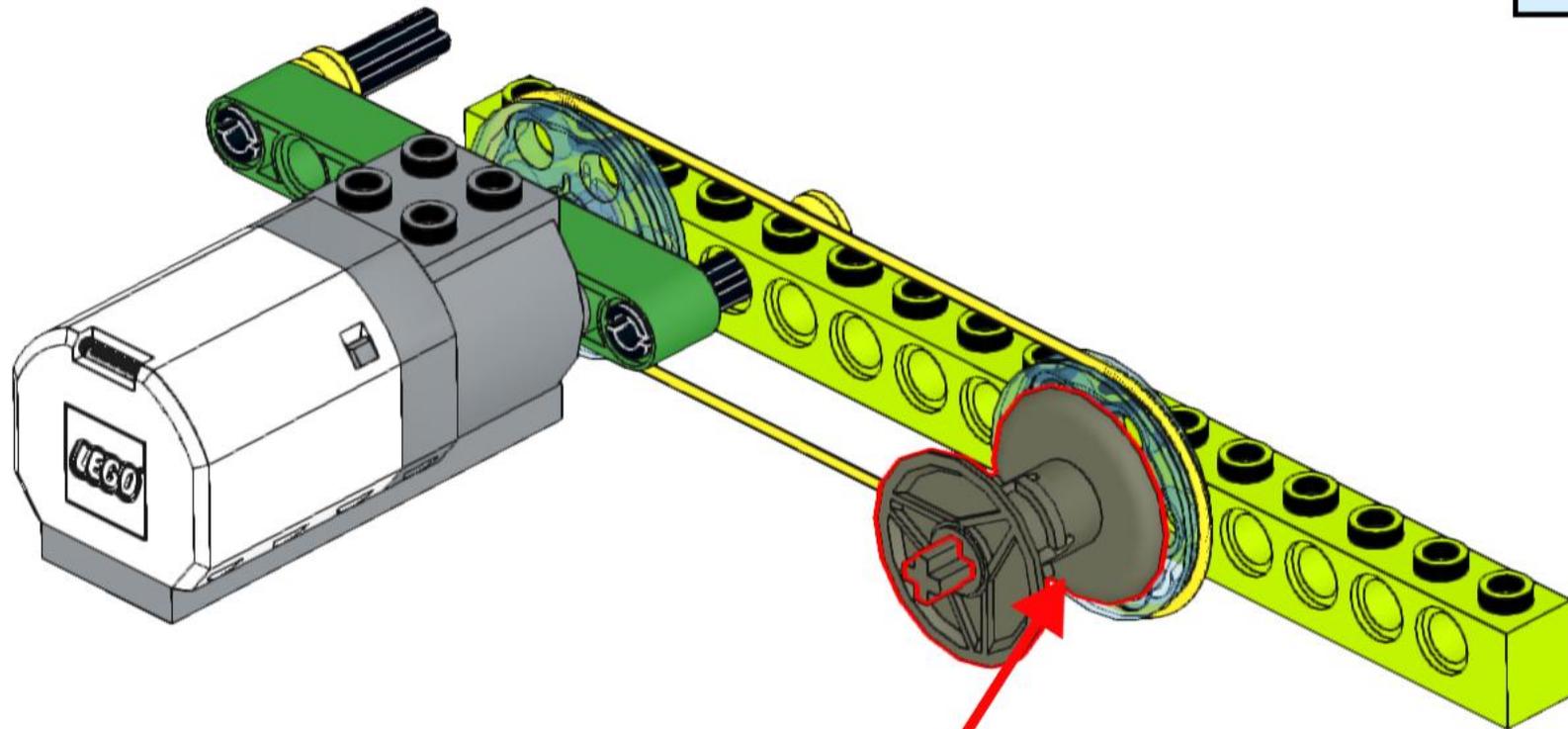
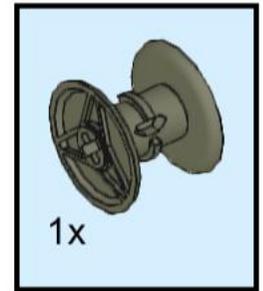
Connect the parts
carefully, tighten
belt at pulleys



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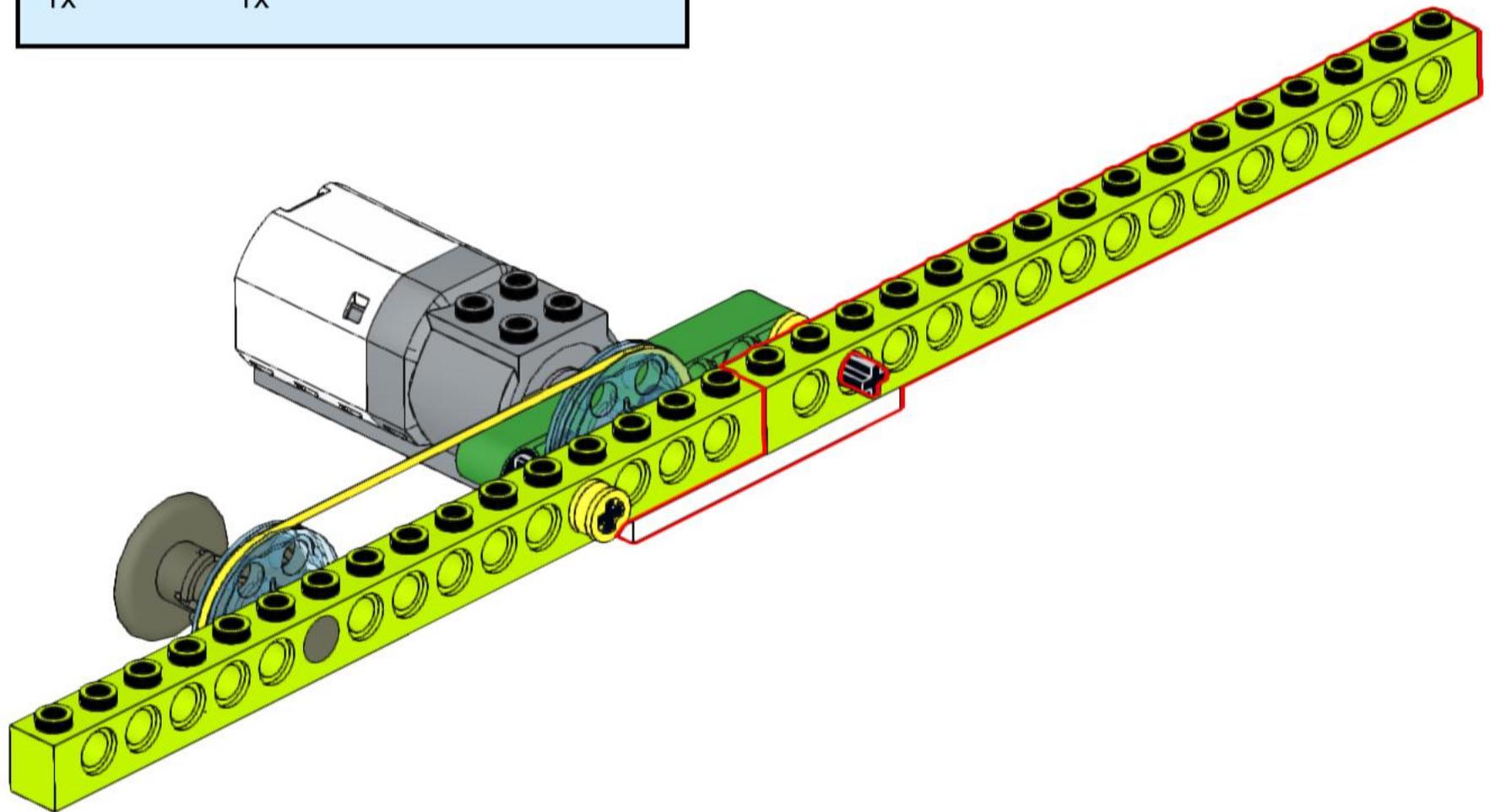
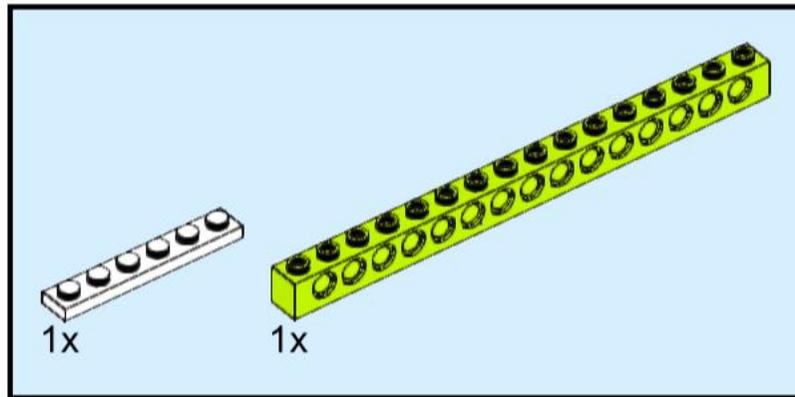
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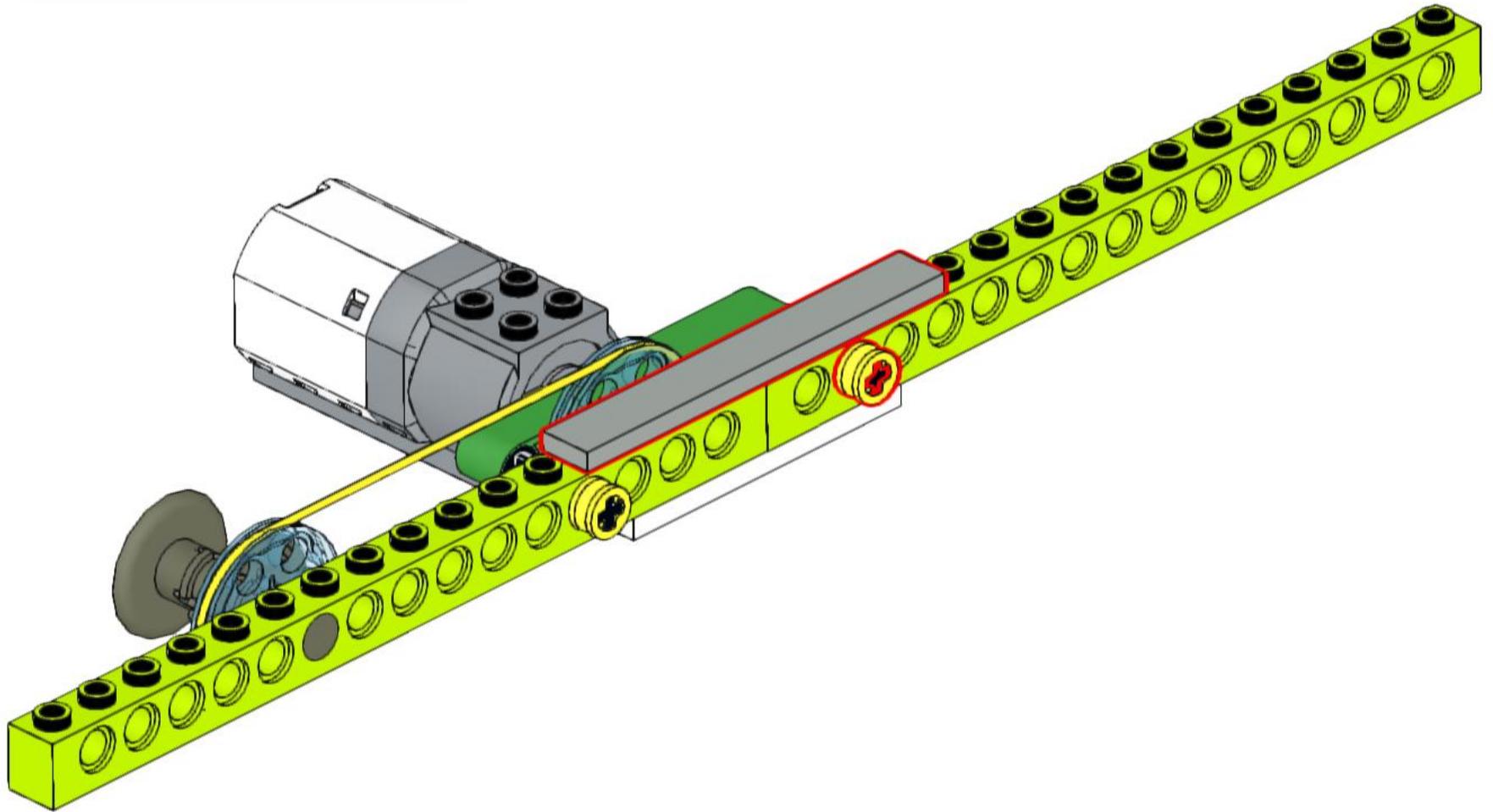
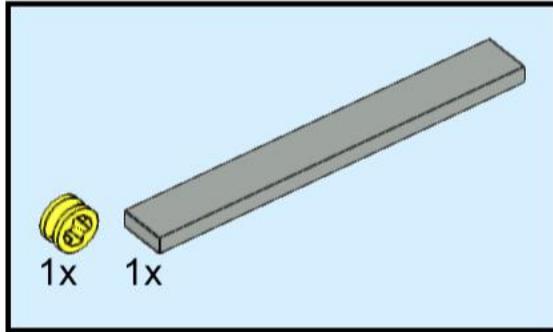
**Wind the cable around
the spool and then set in
on the axle**



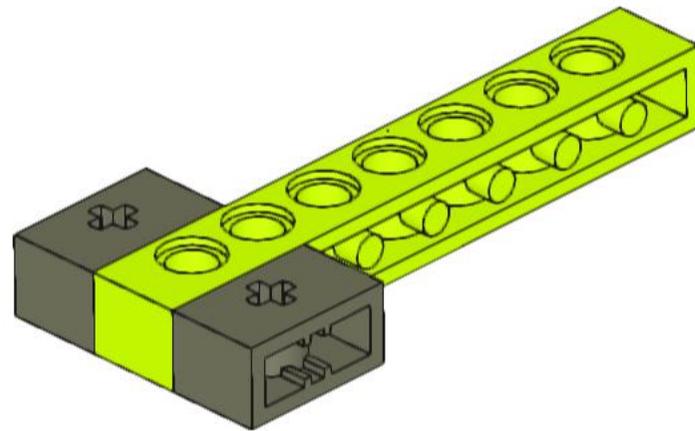
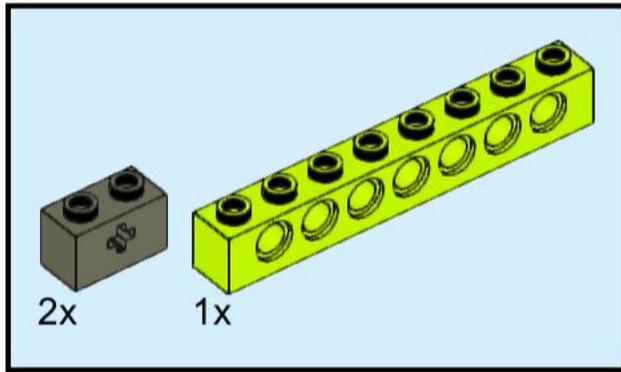
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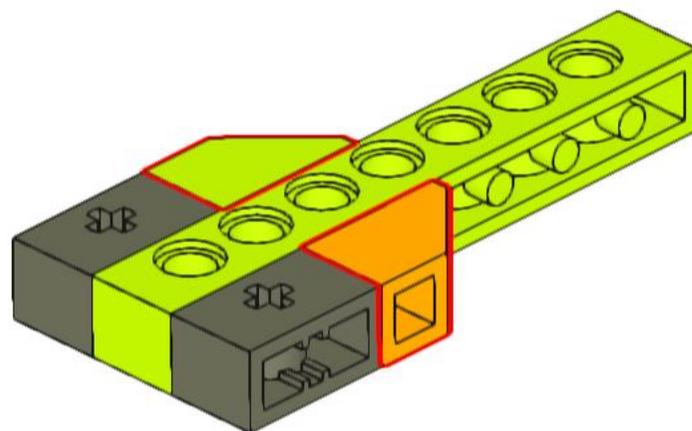
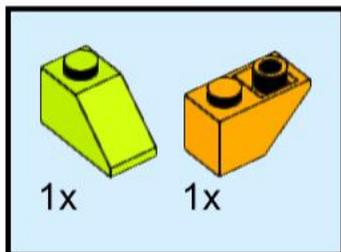
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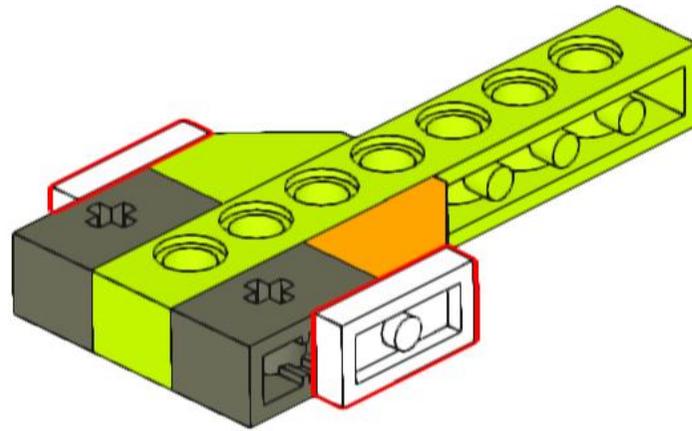
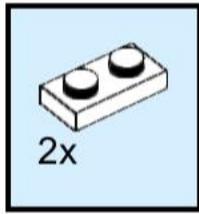
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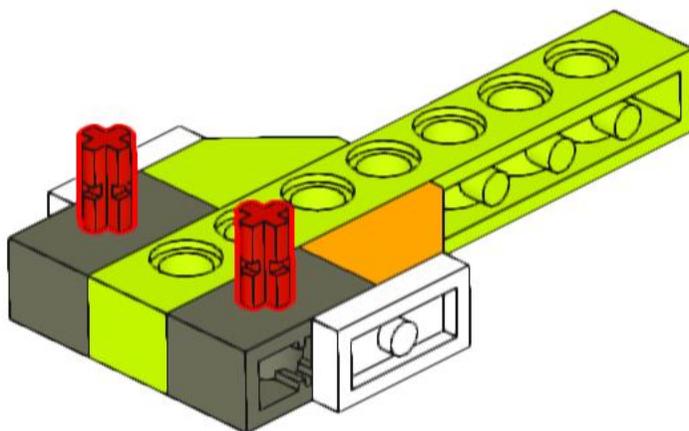
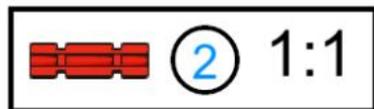
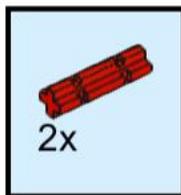
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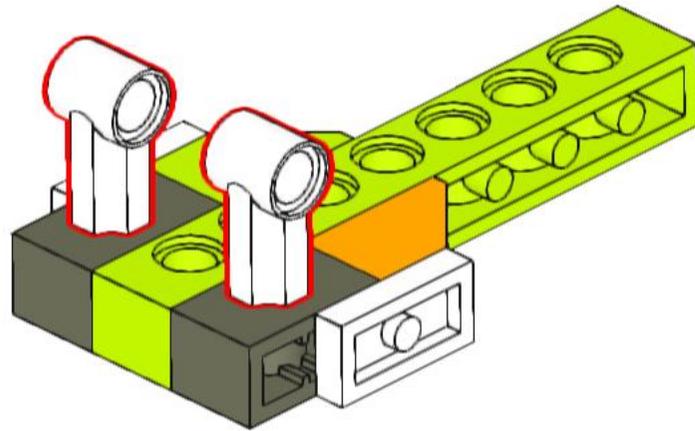
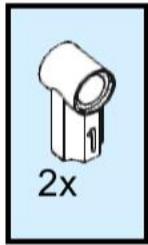
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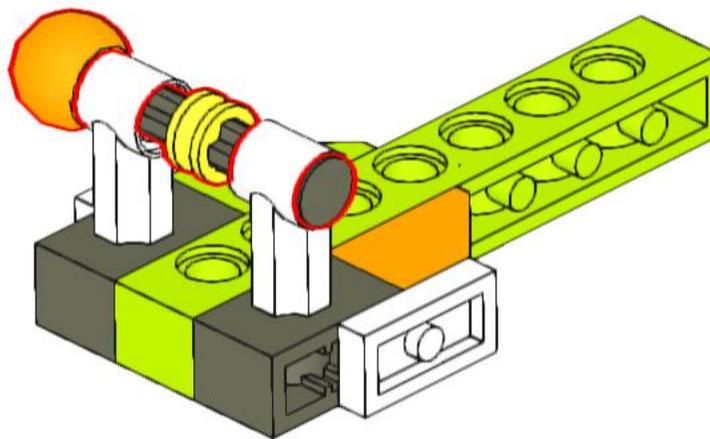
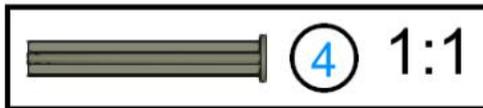
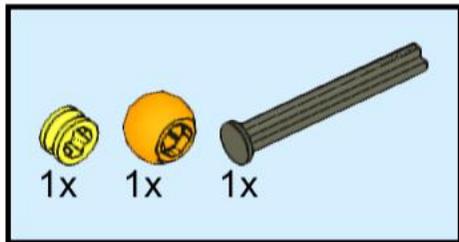
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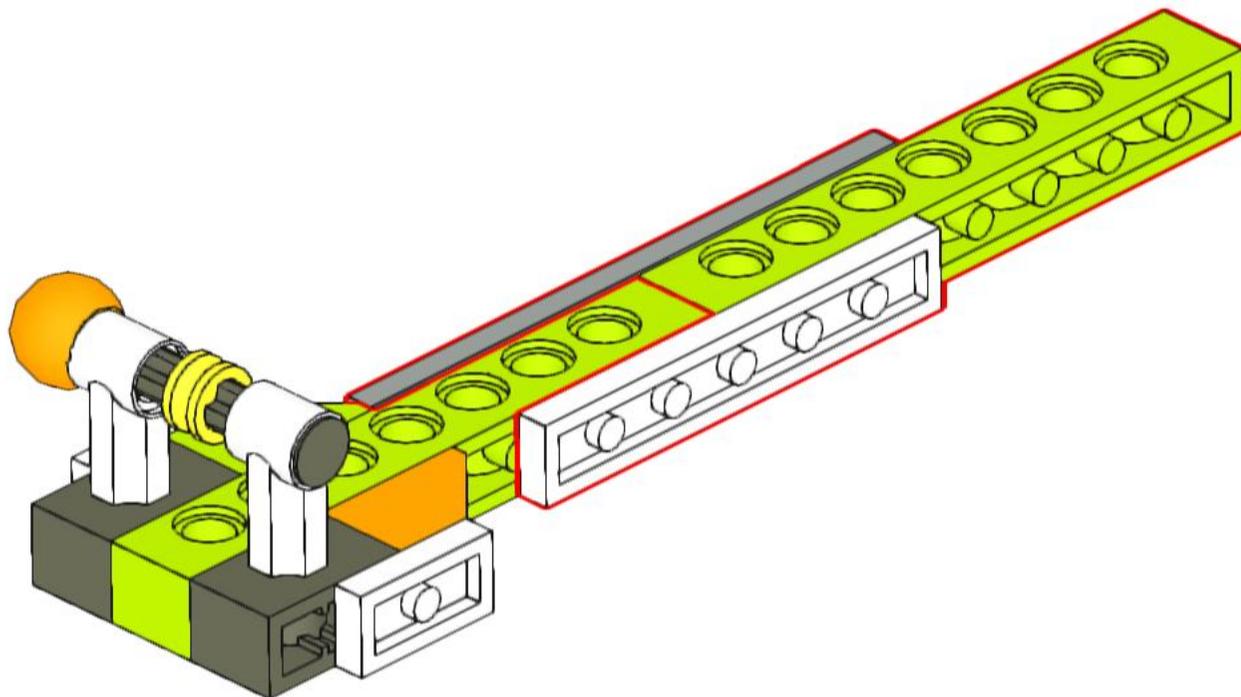
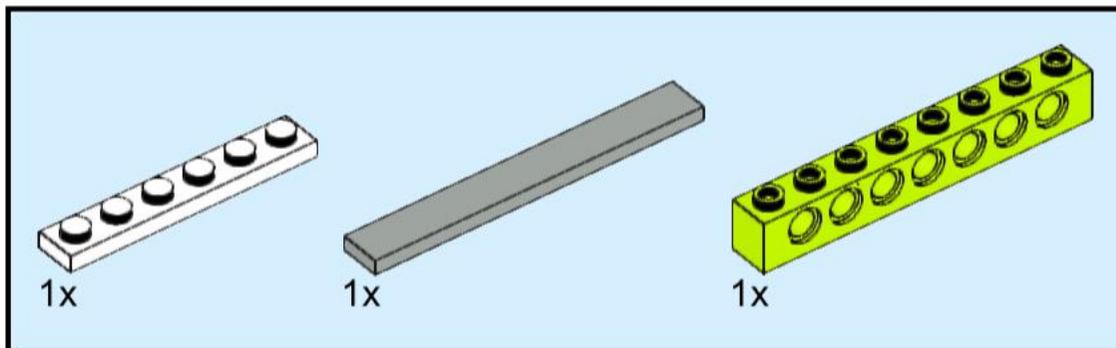
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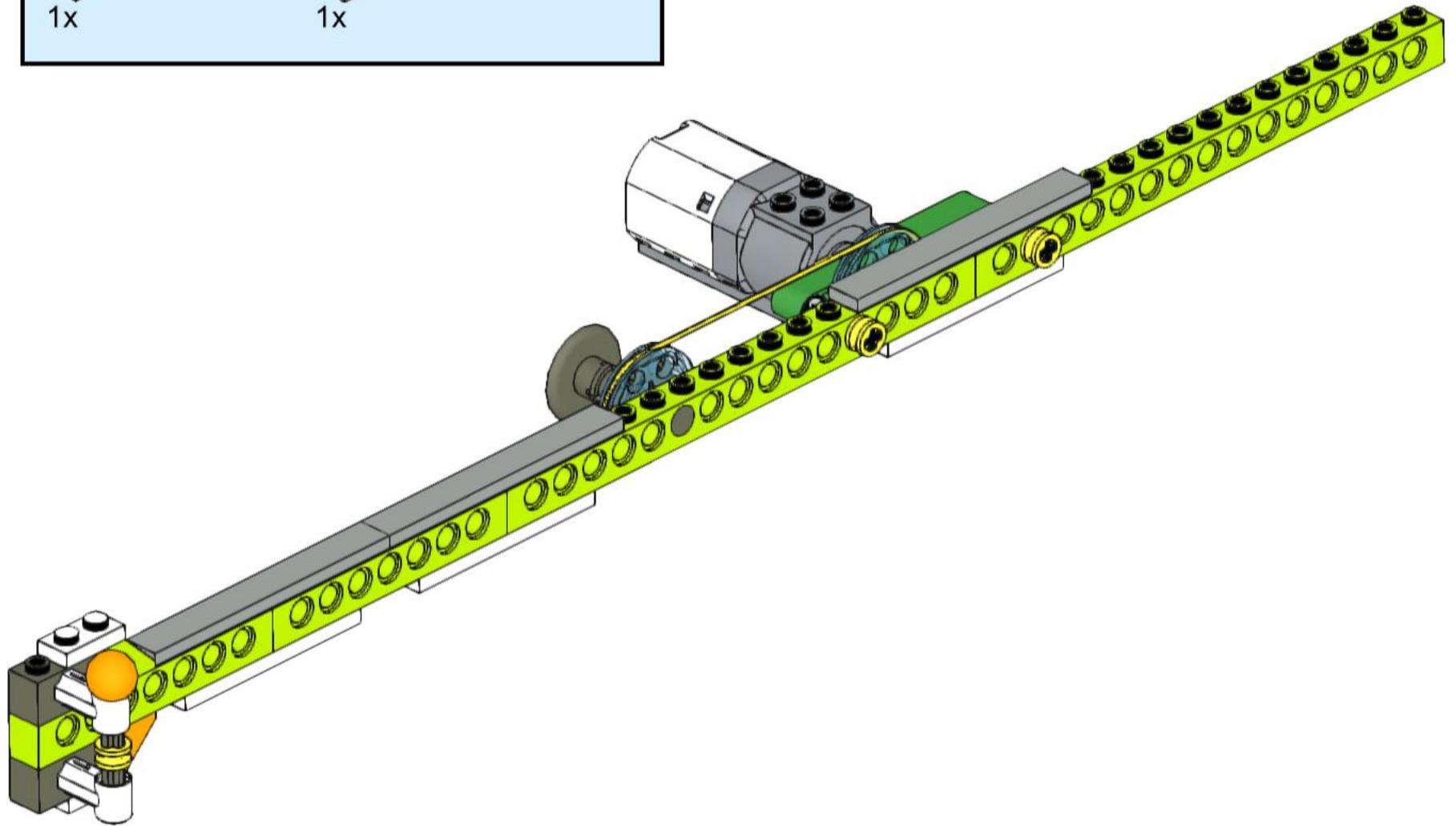
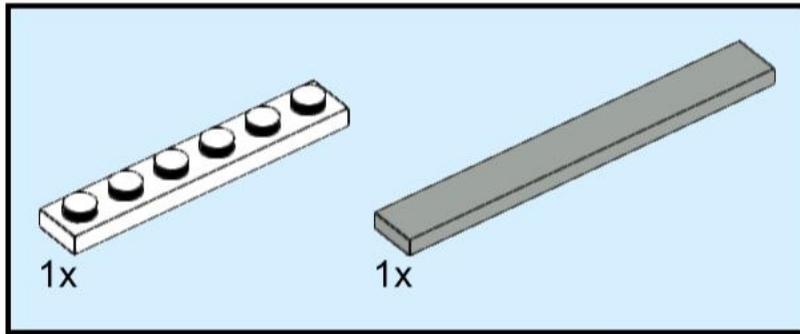
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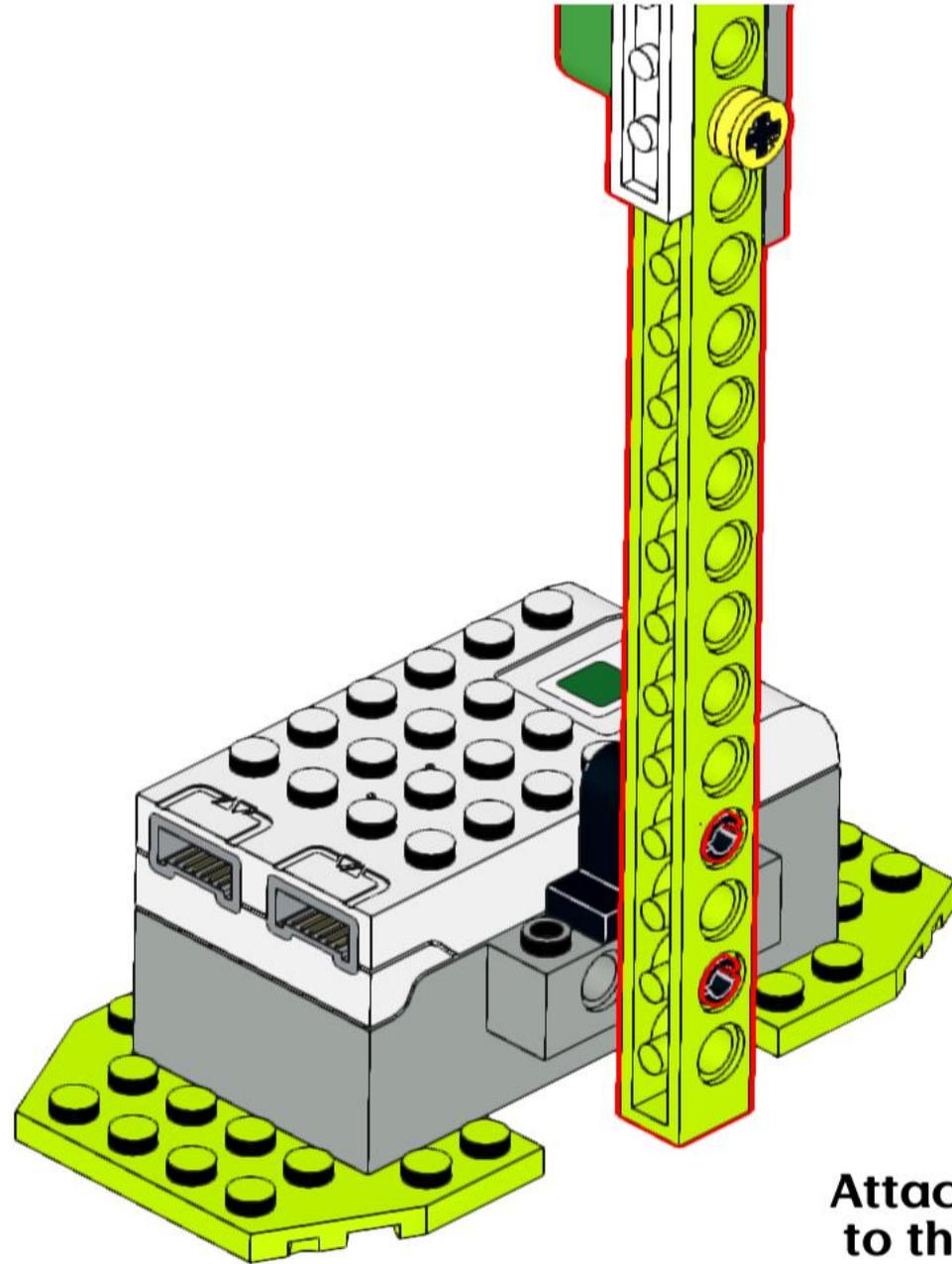
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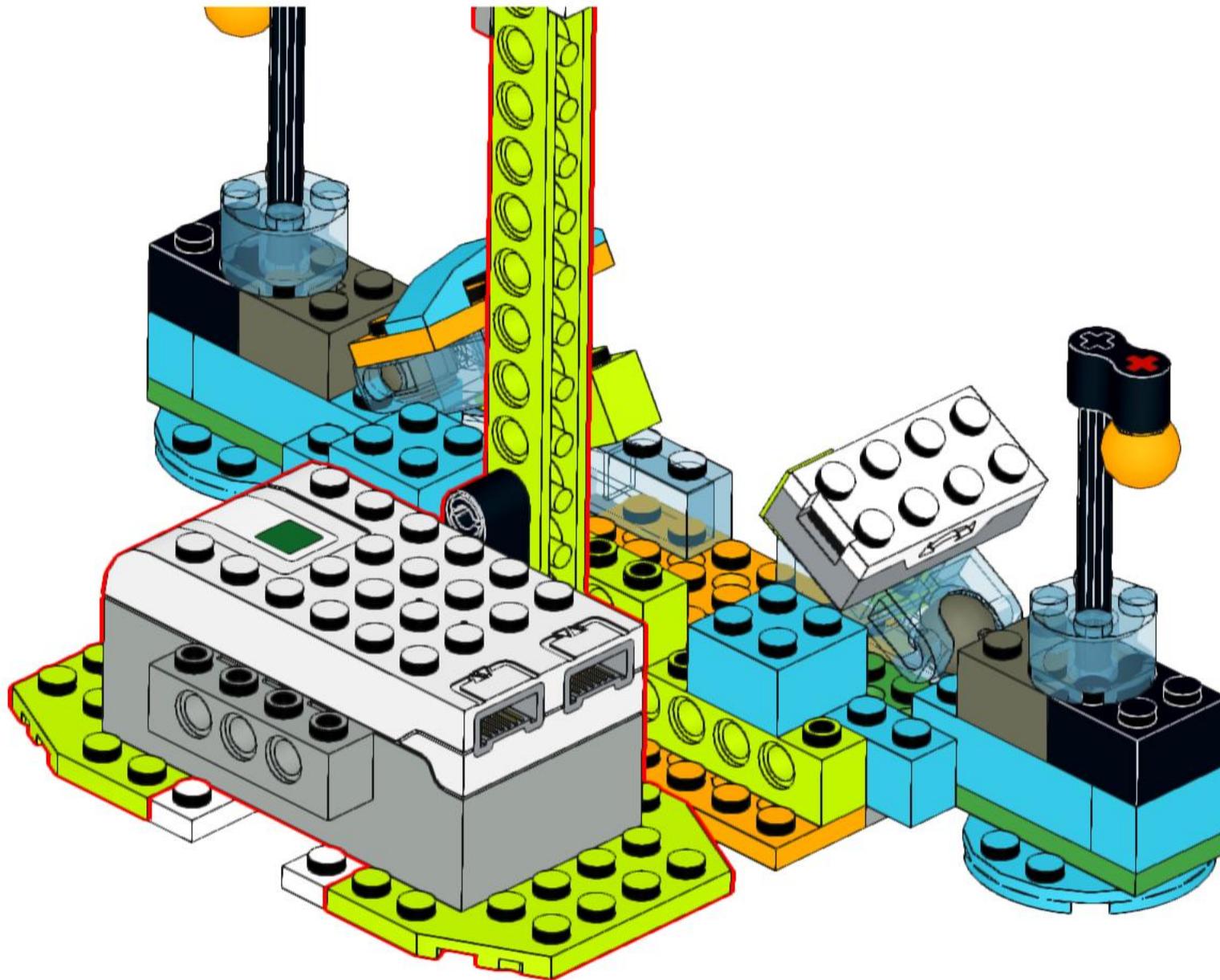


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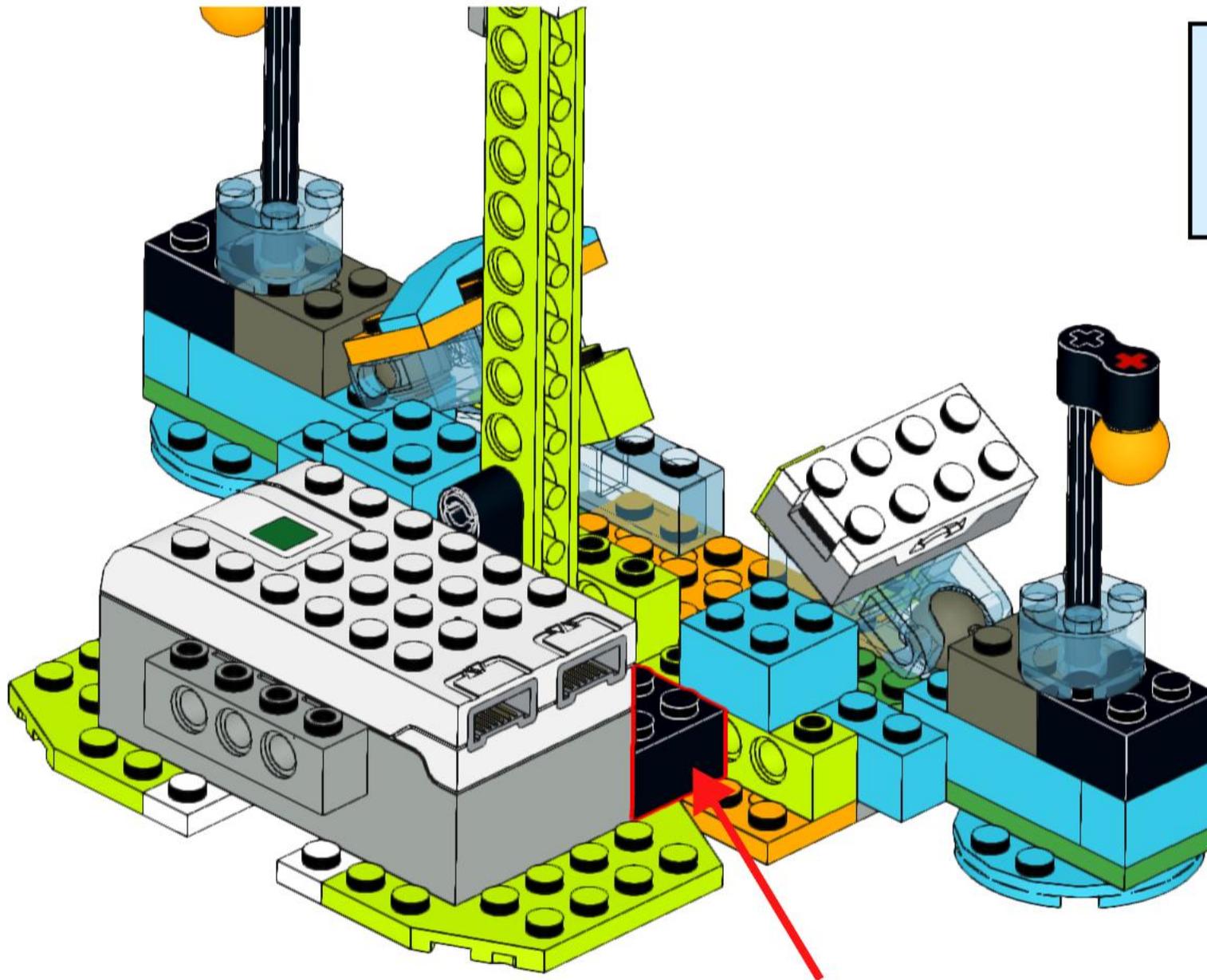
**Attach the mast
to the smarthub**

47



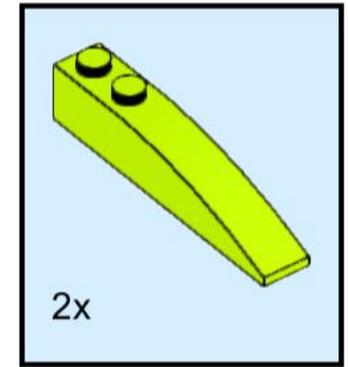
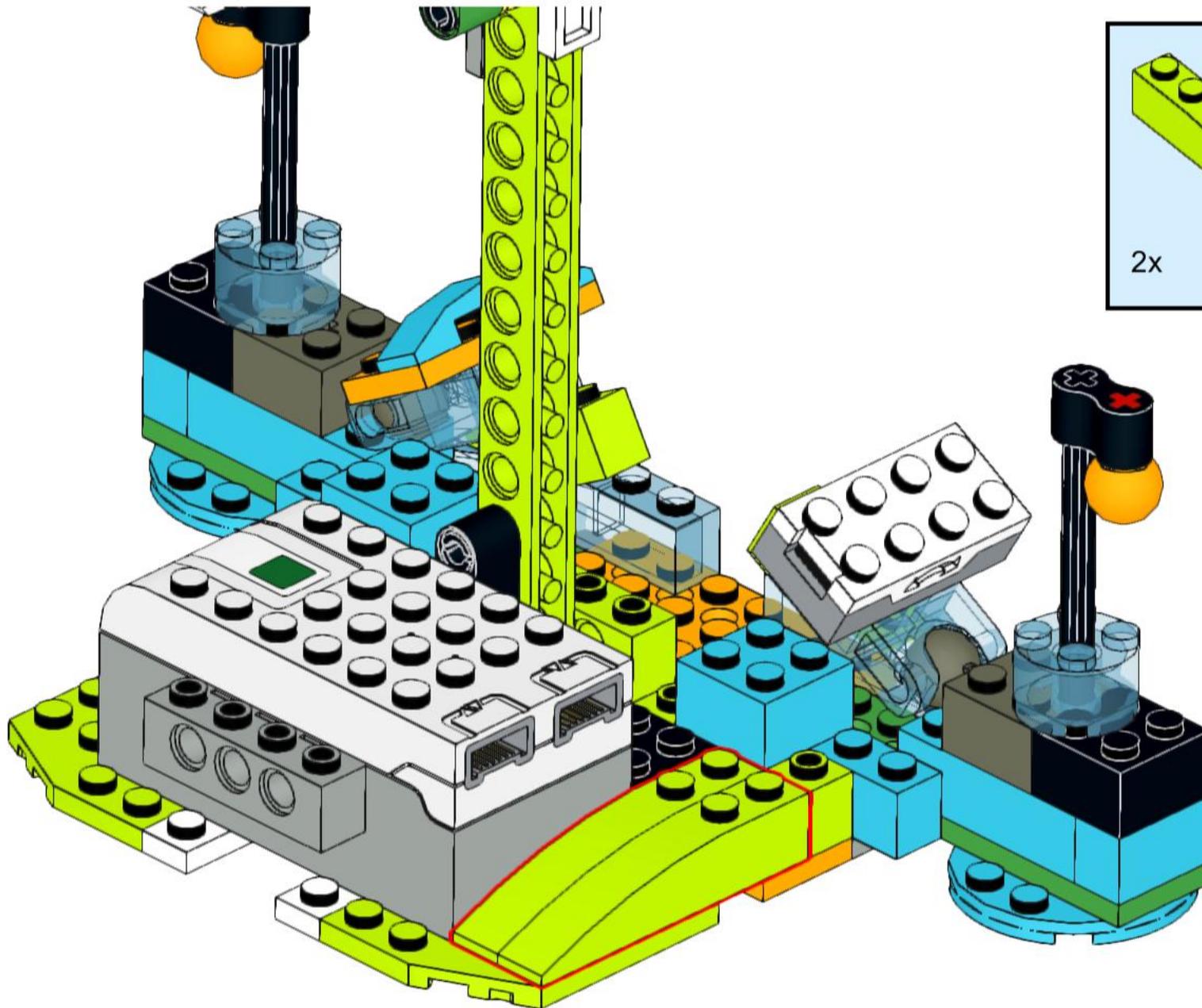
**Connect smarthub to
the platform**

48

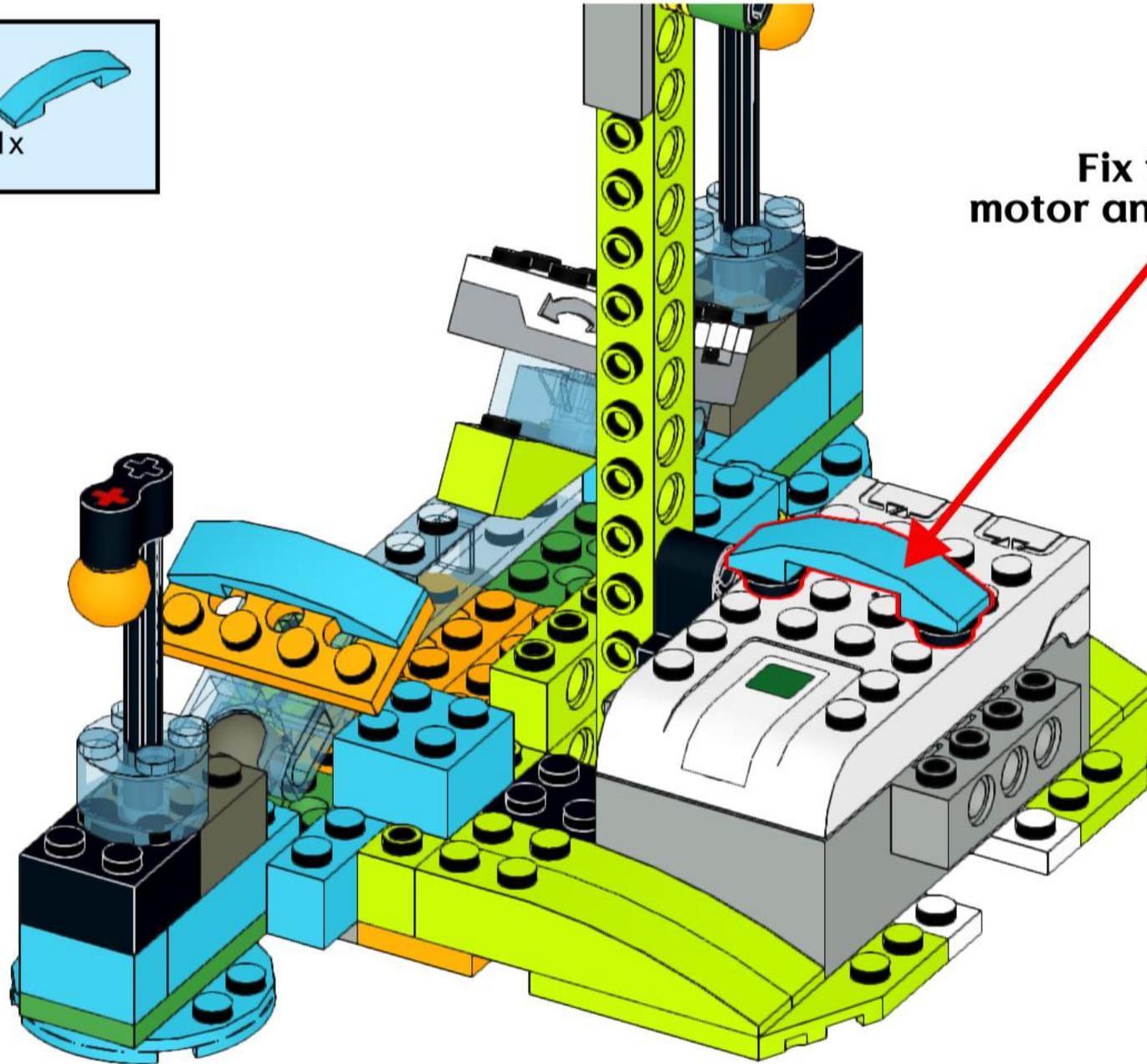
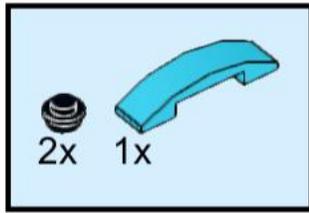


Set from both sides

49

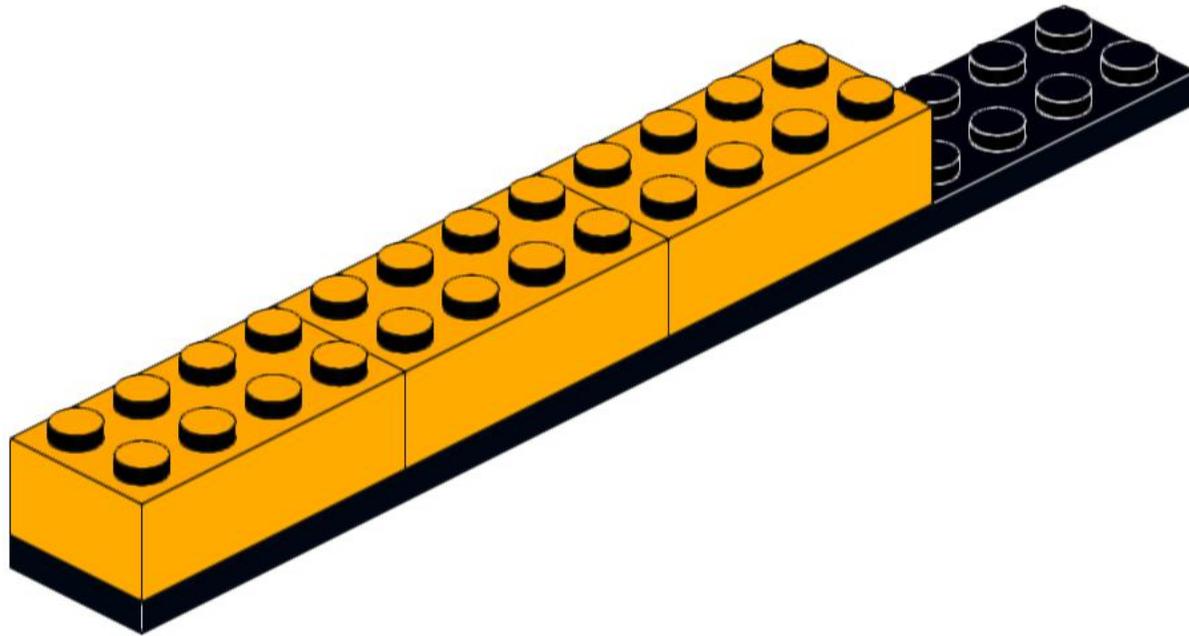
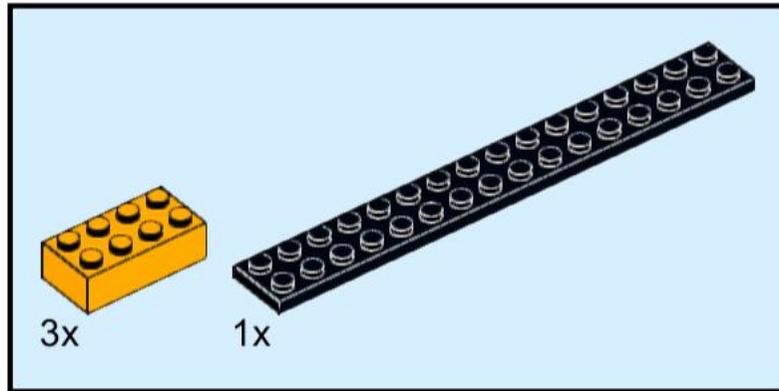


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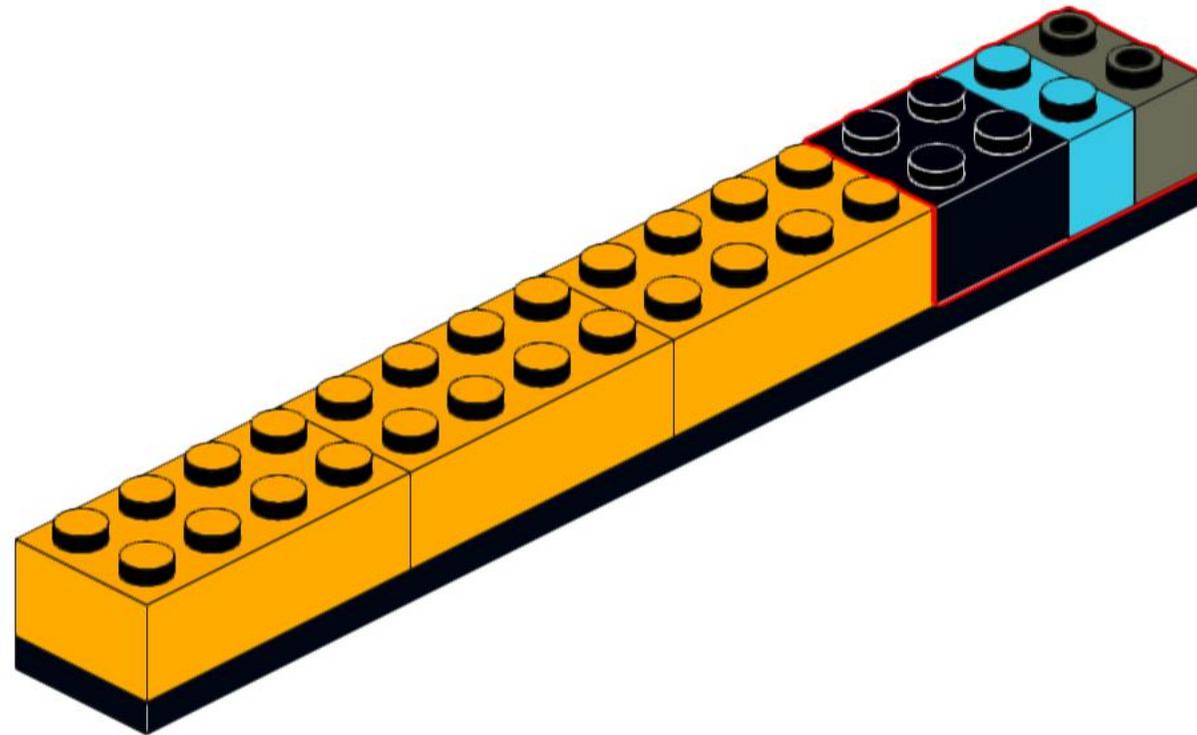
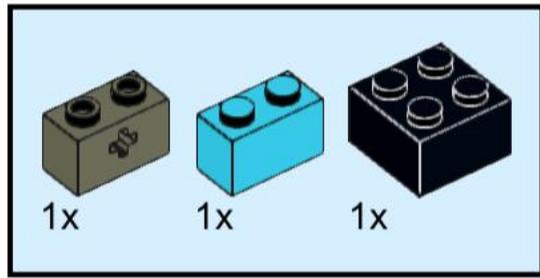


Fix the wires of motor and tilt sensor

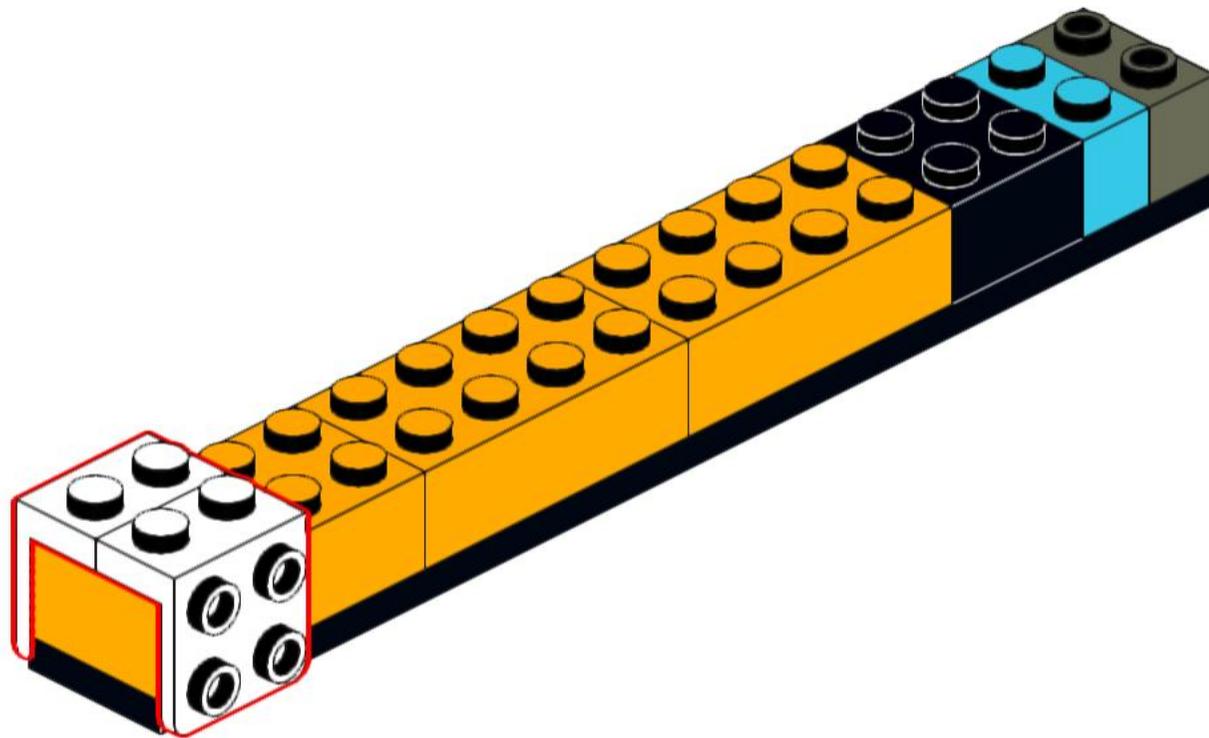
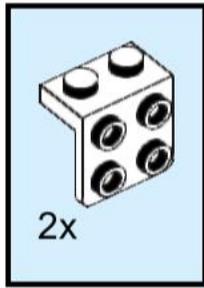
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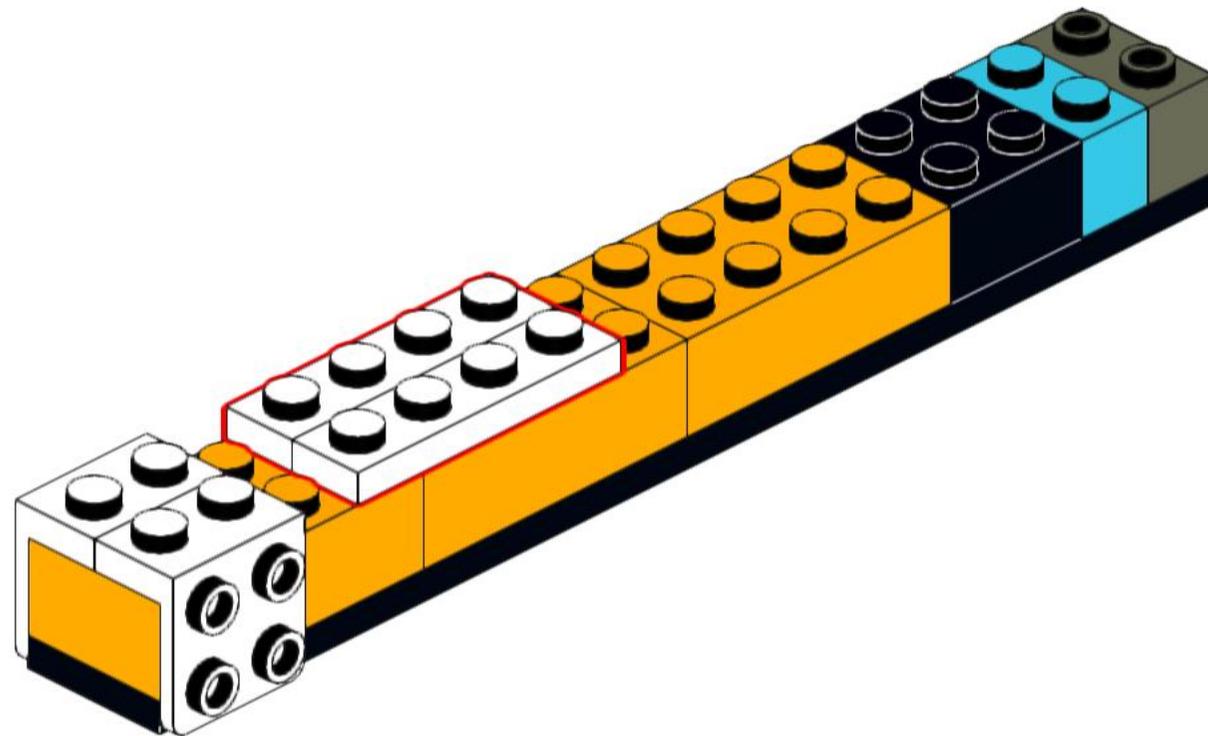
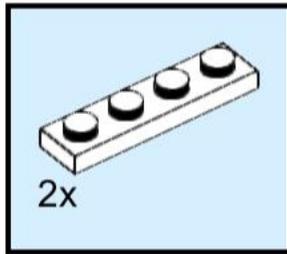
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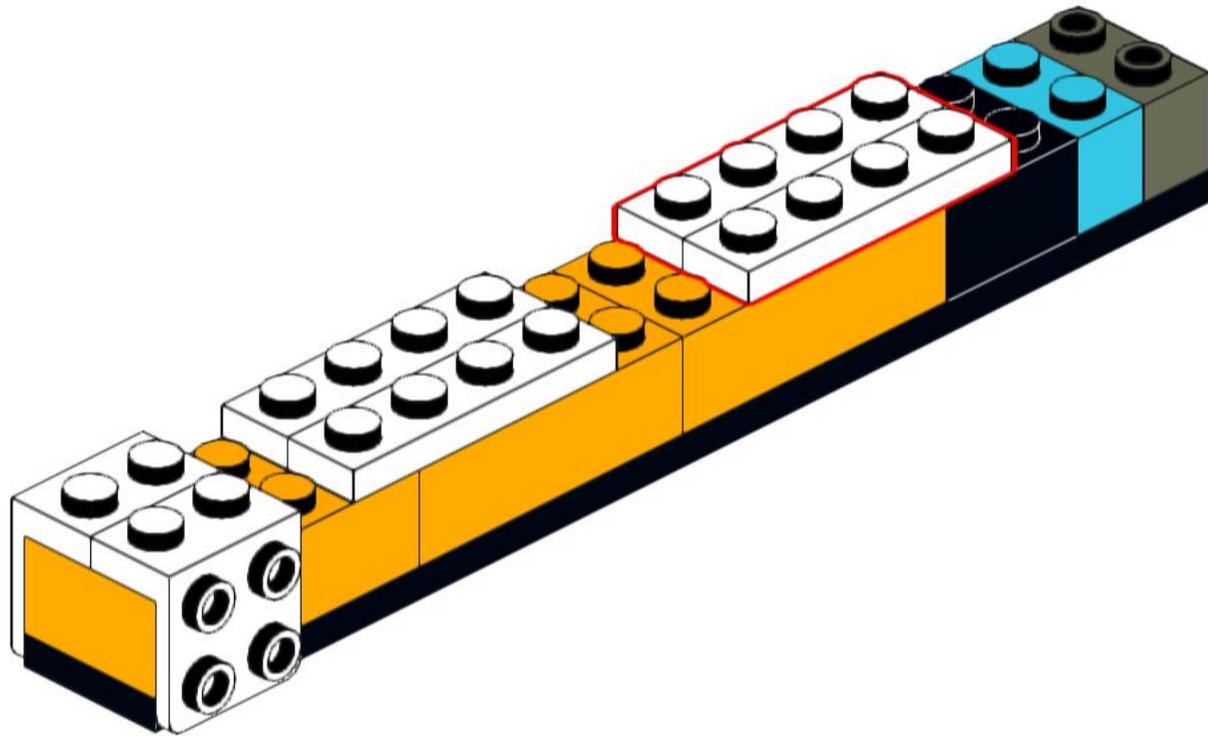
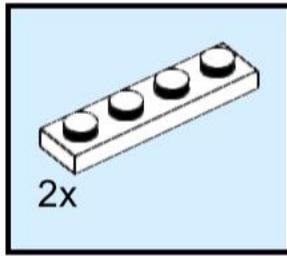
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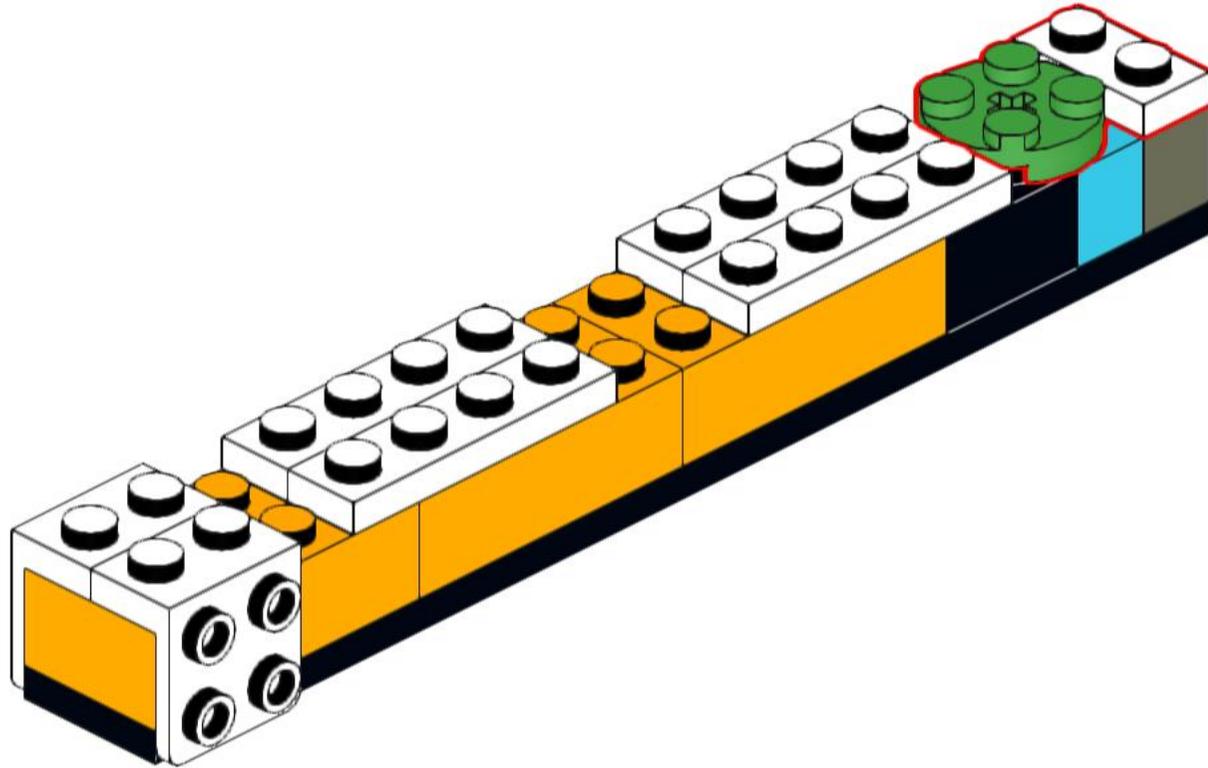
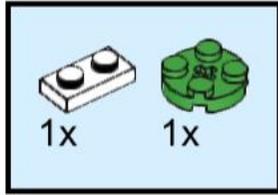
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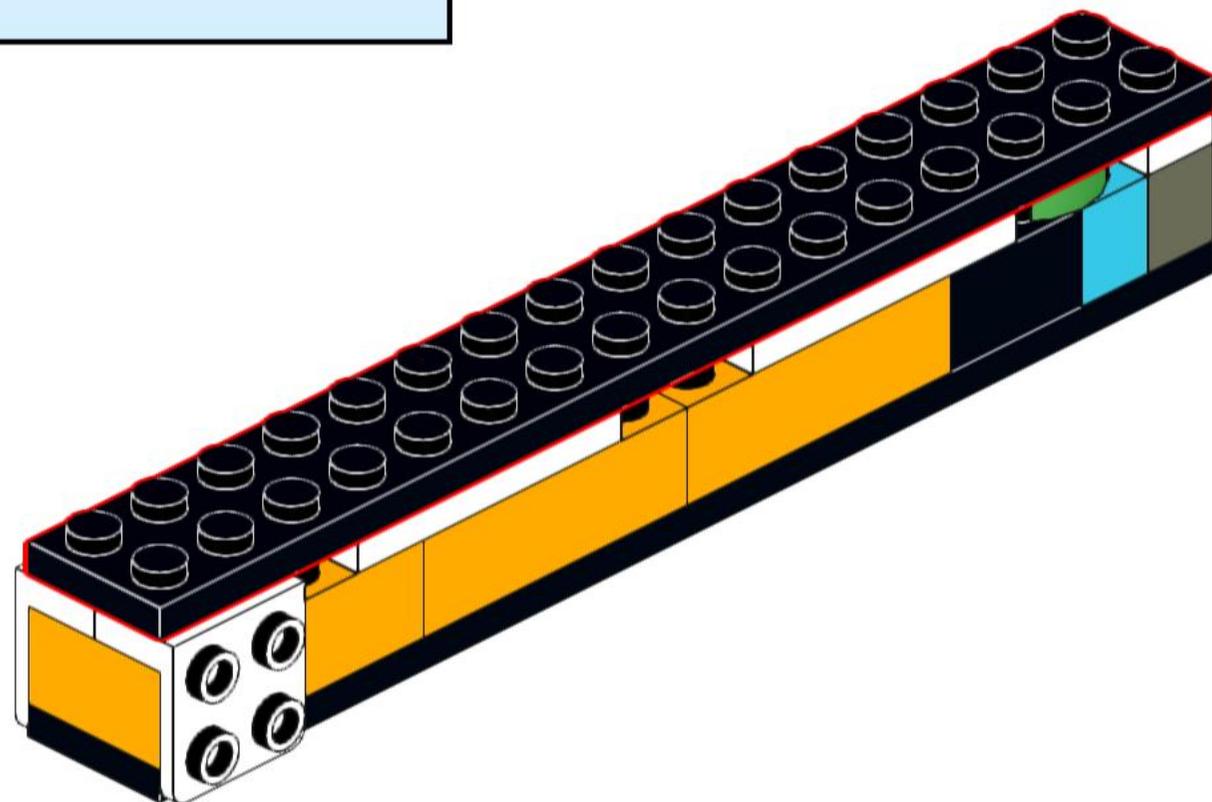
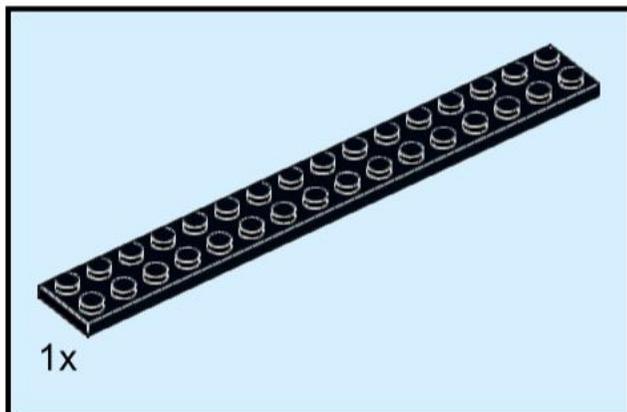
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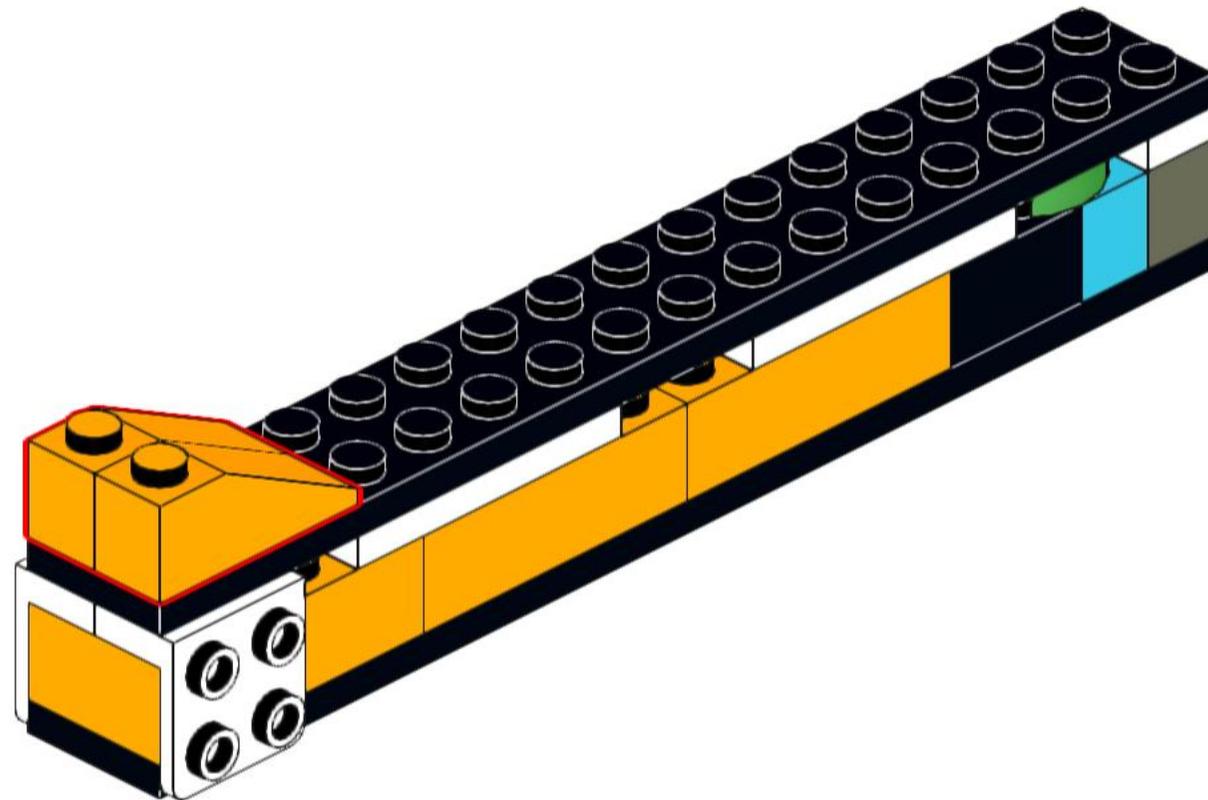
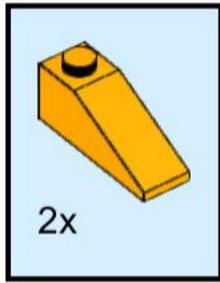
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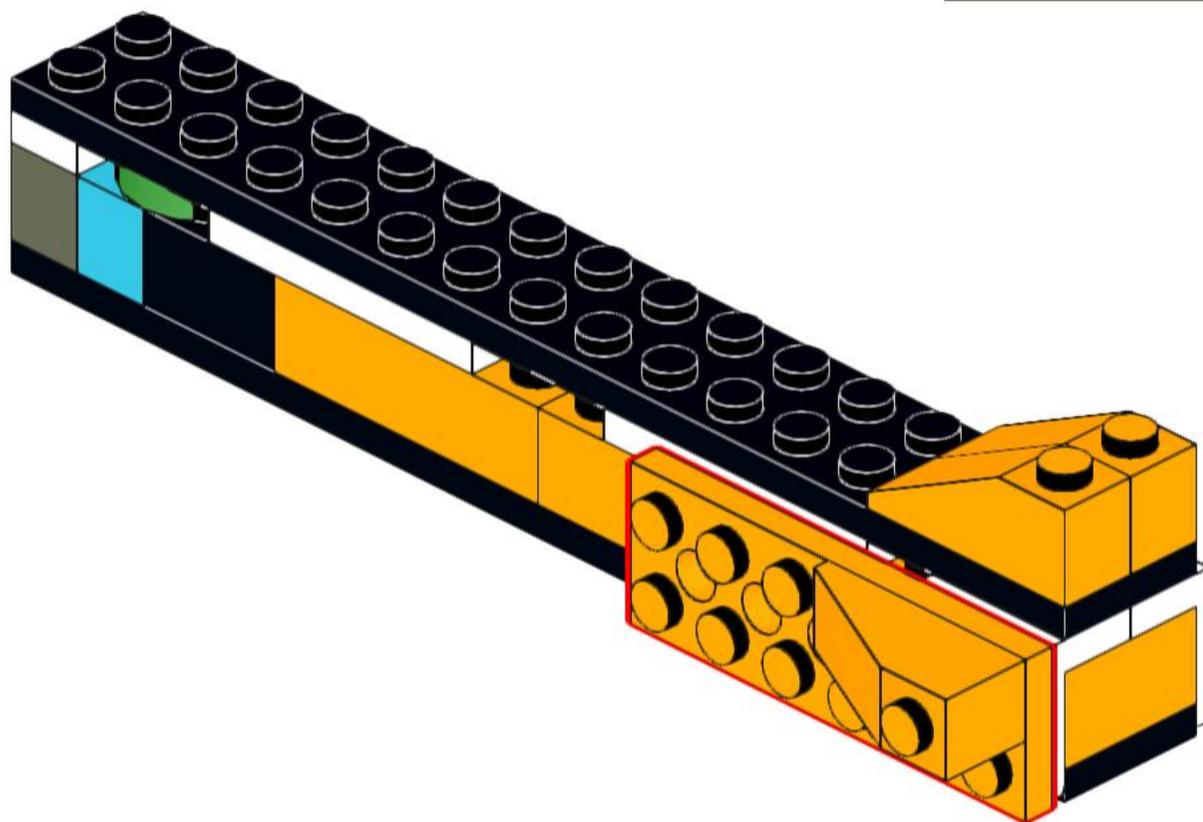
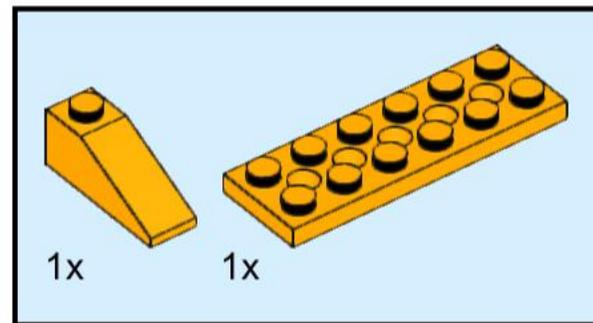
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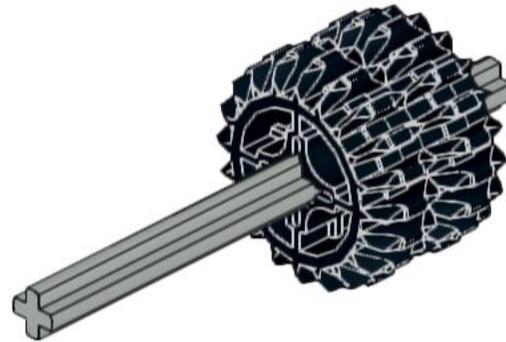
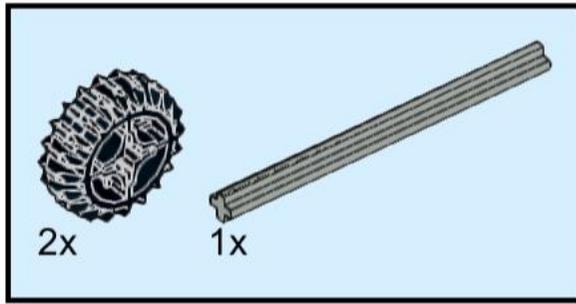
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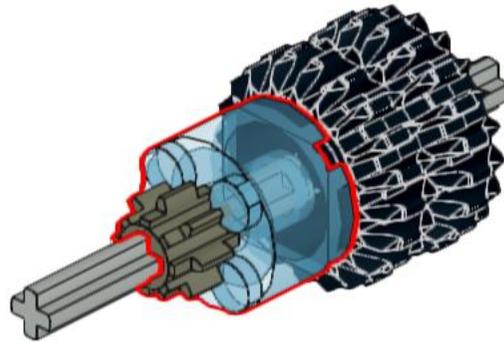
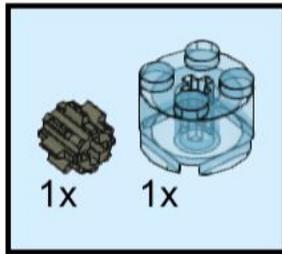
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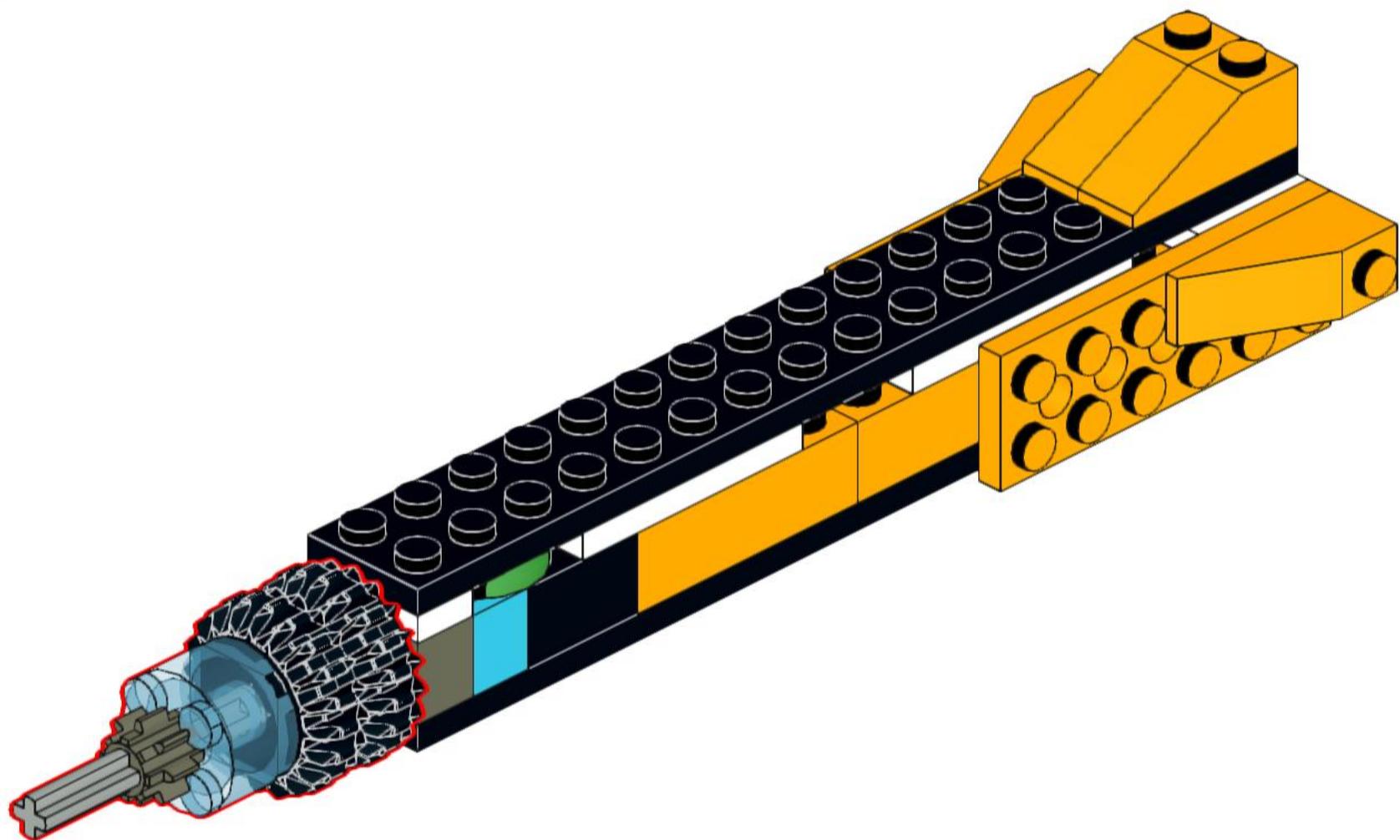
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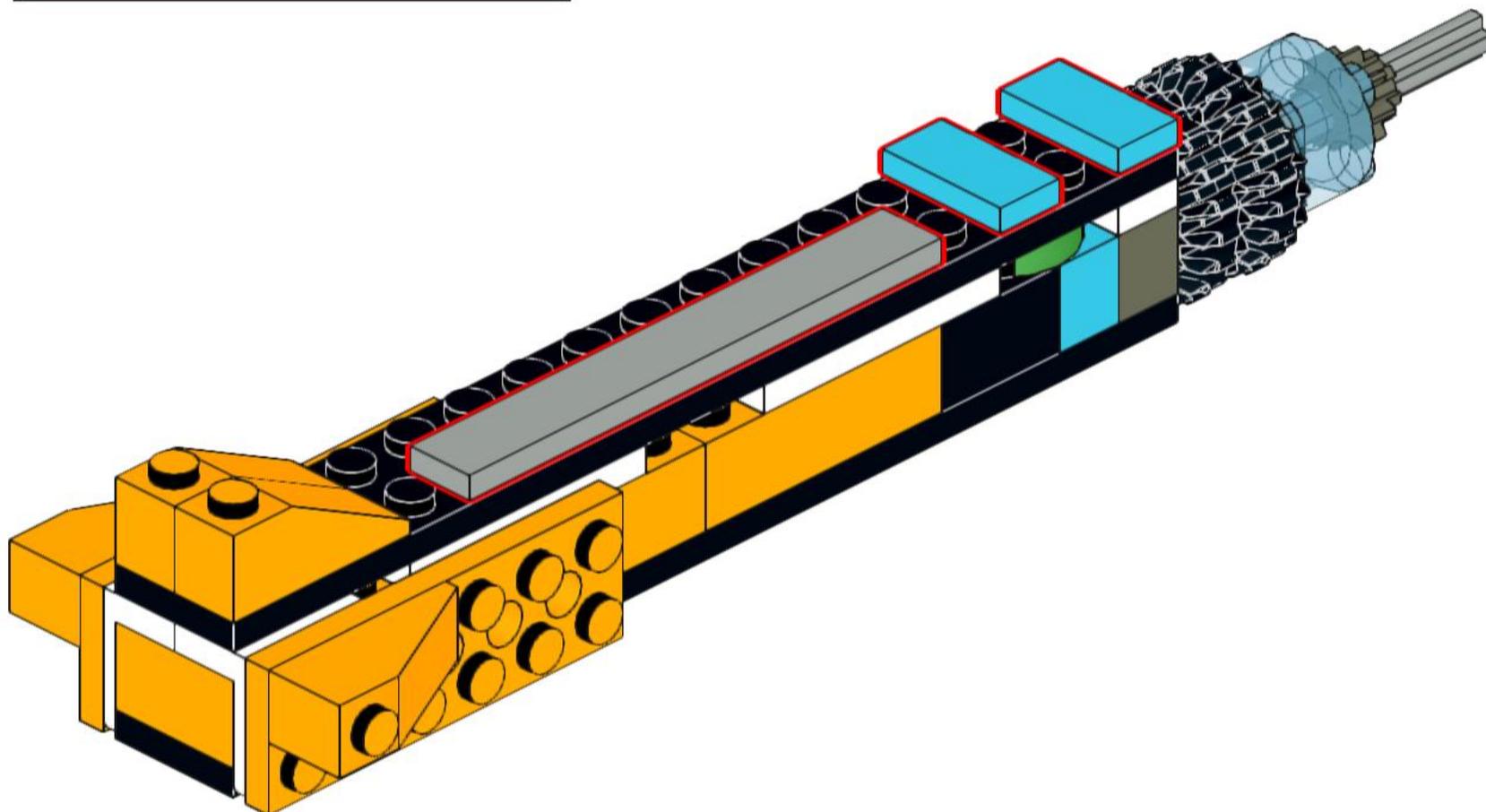
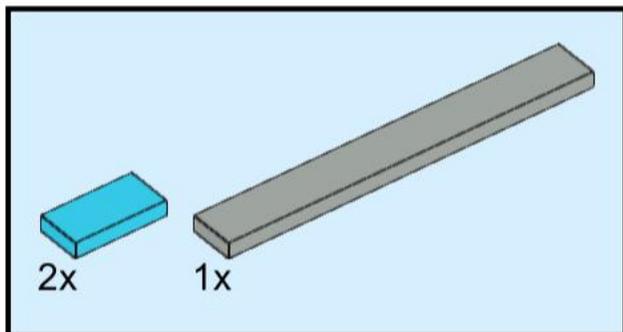
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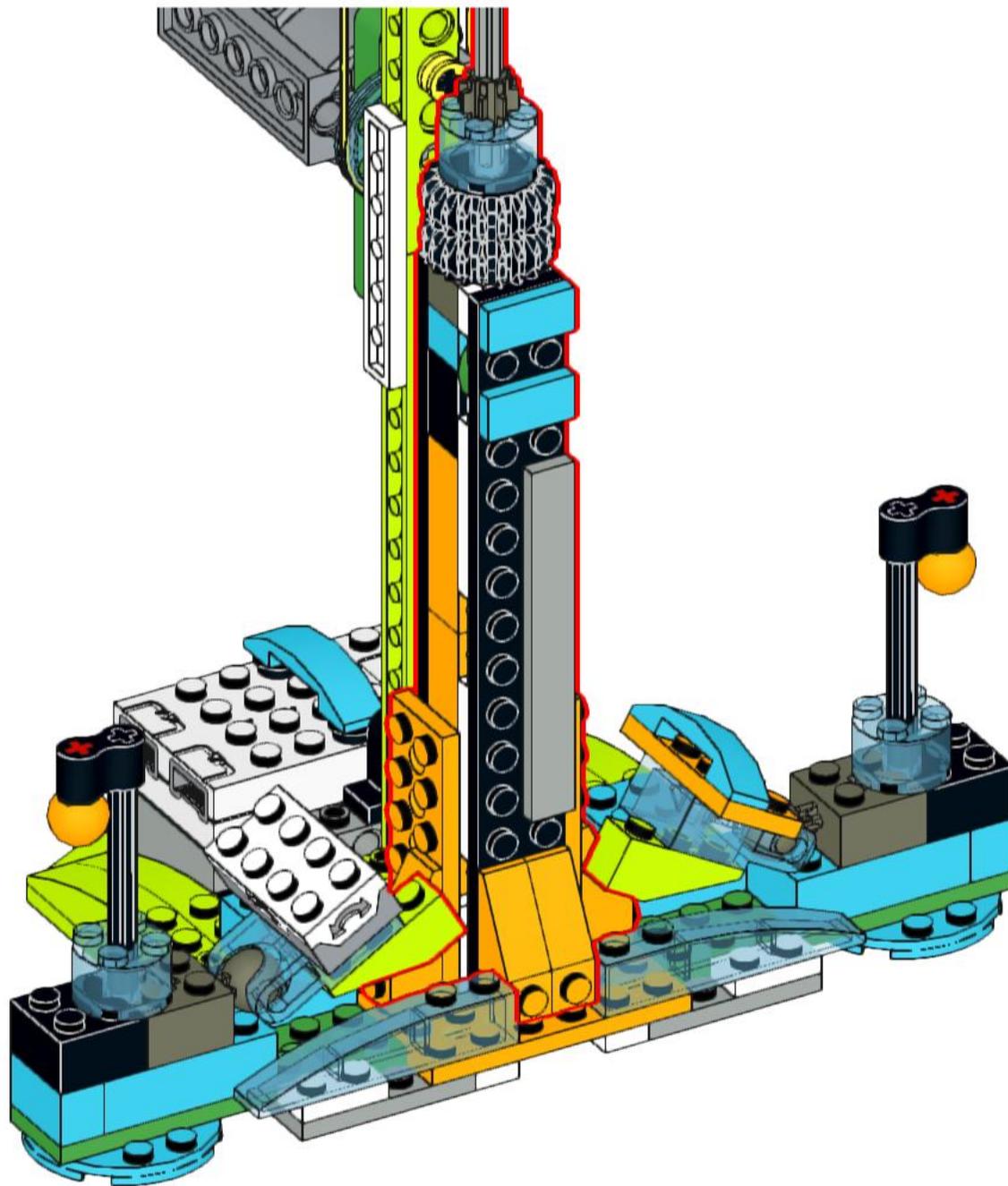
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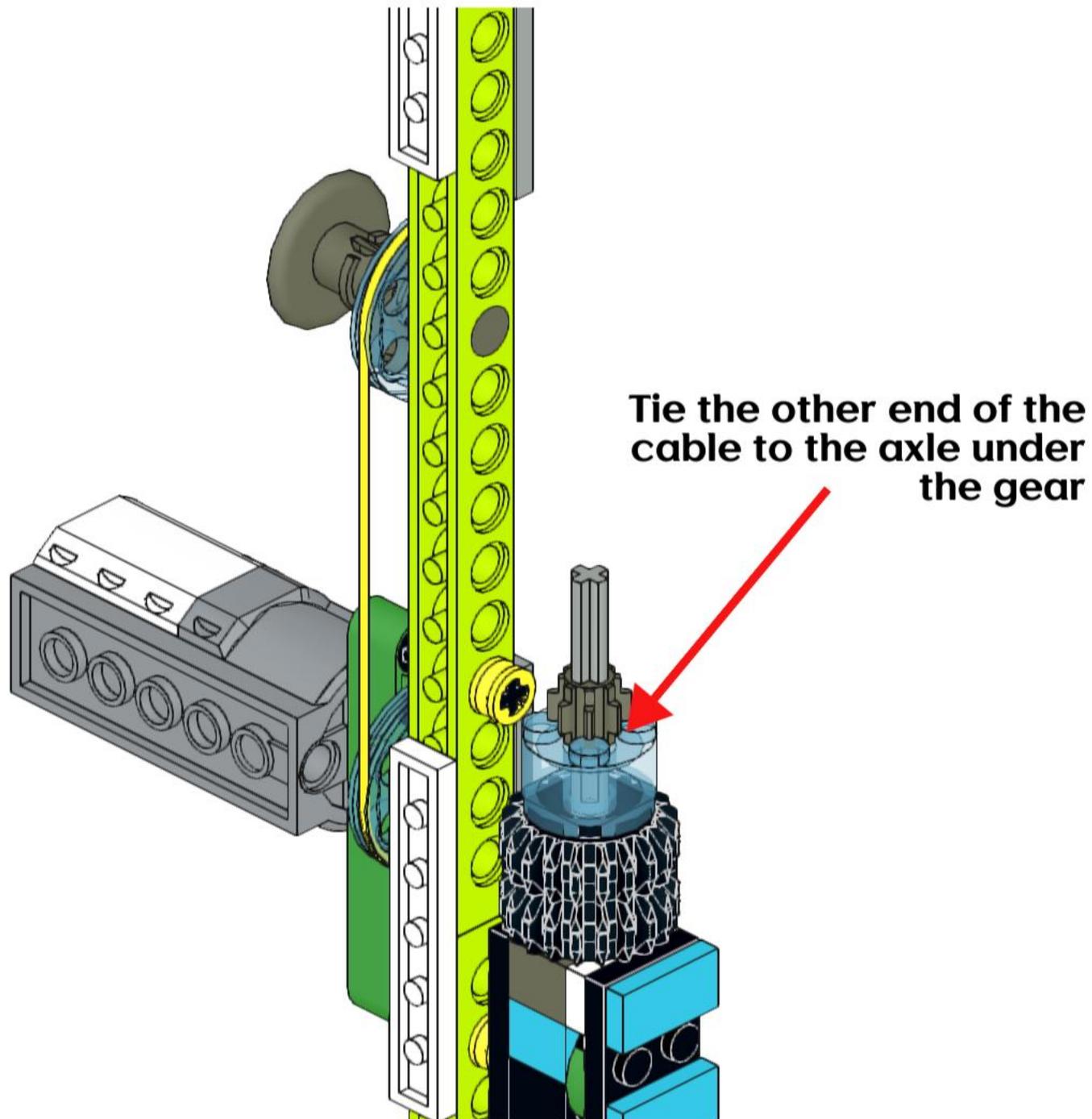
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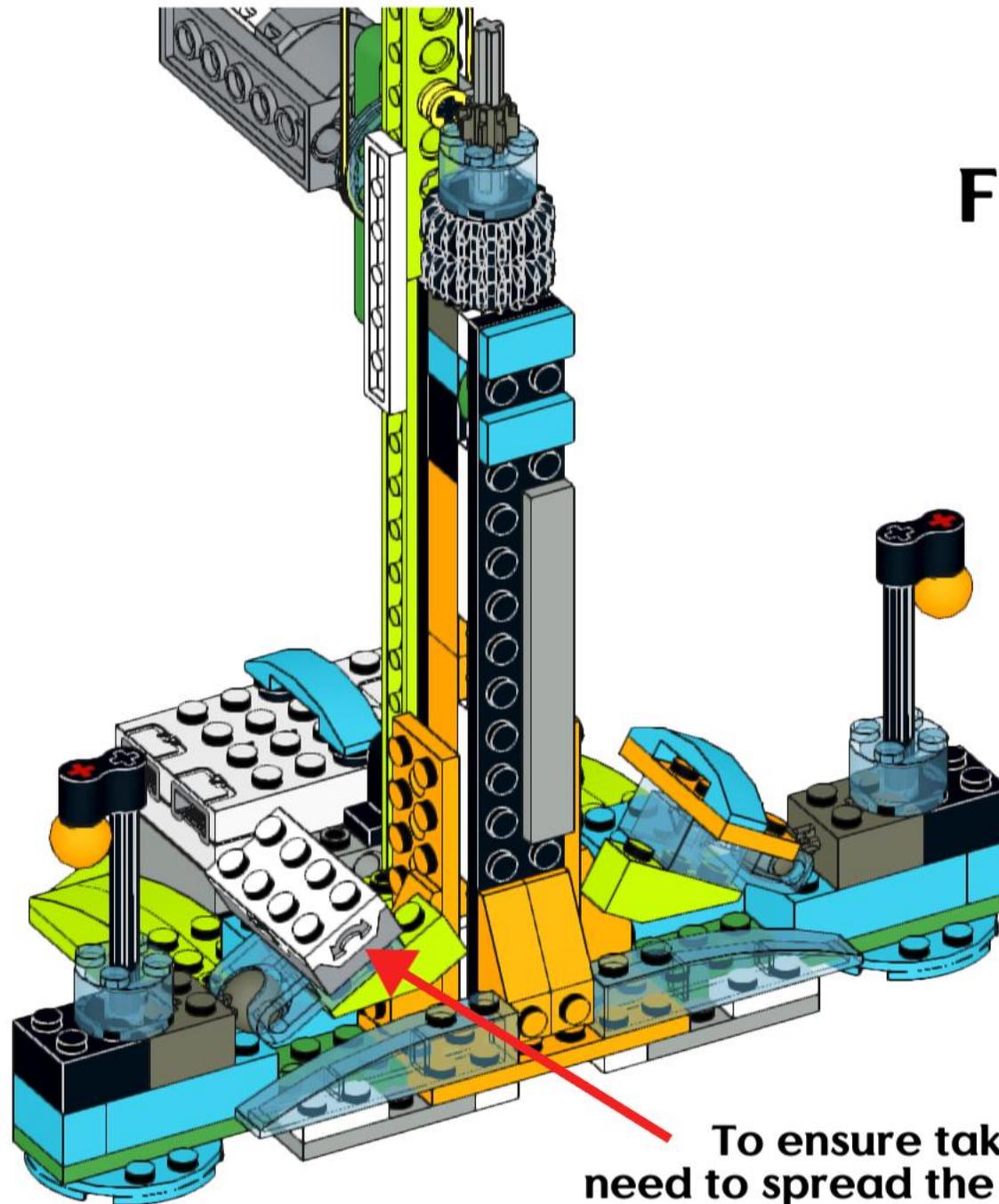


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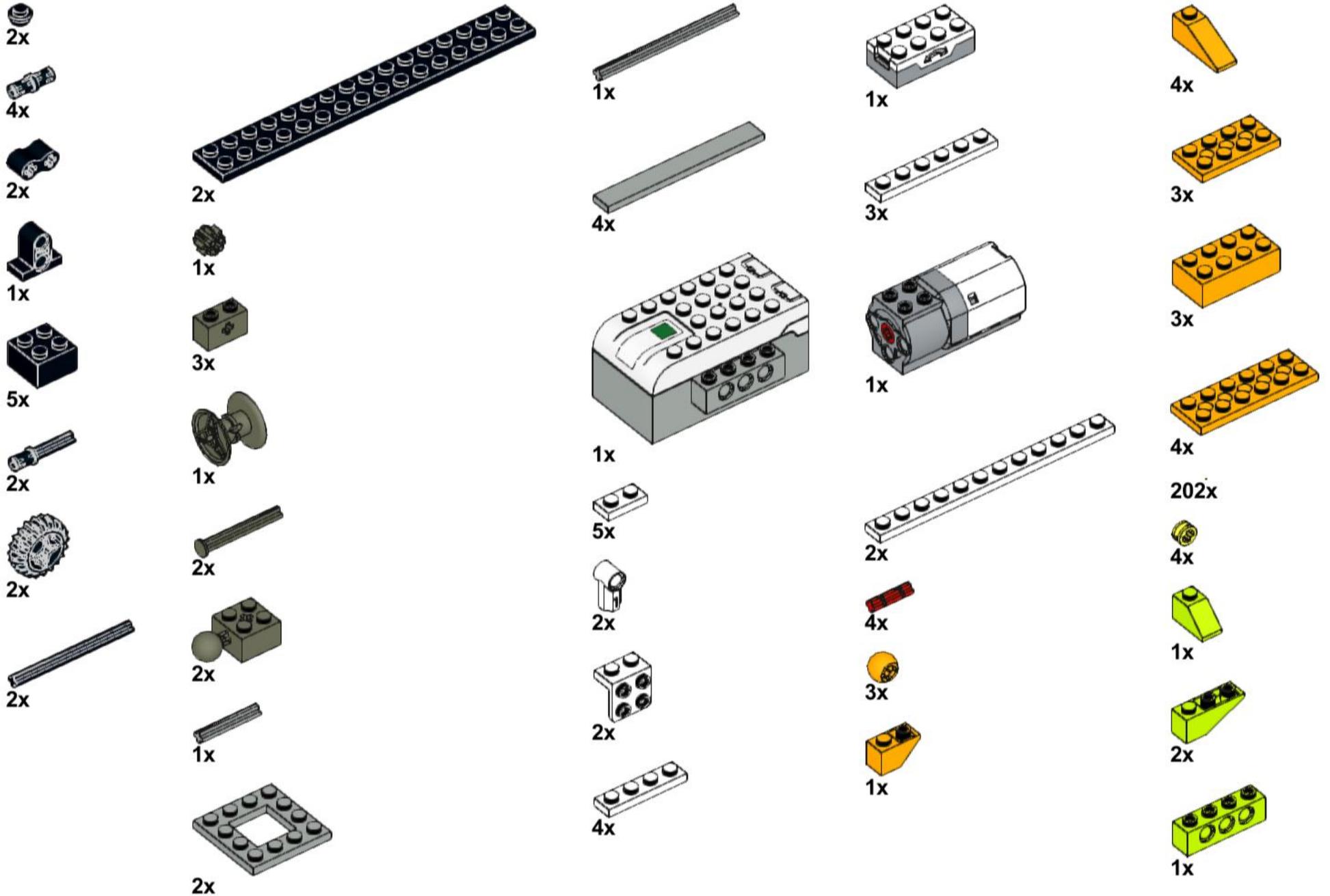
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FINISH!

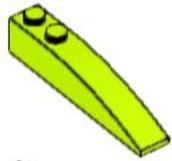


To ensure takeoff, you need to spread the platform latches to the sides

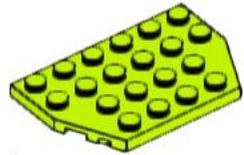
PARTS LIST



PARTS LIST



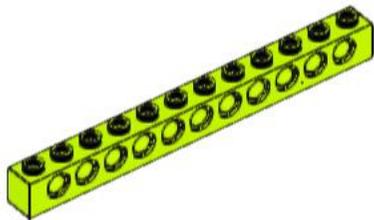
4x



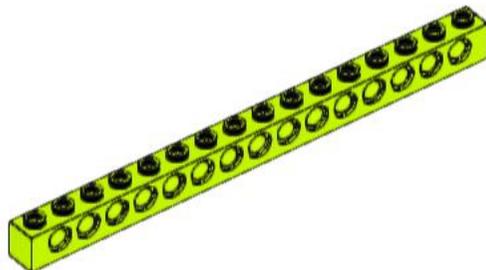
2x



2x



1x



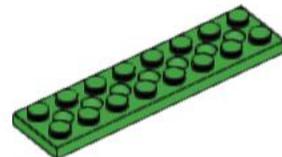
2x



1x



1x



2x



2x



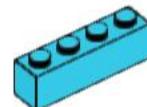
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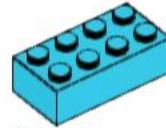
2x



2x



2x



2x



2x



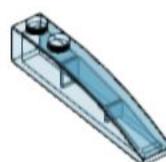
3x



2x



2x



2x

Example of program

Countdown timer



Control by the tilt sensor



Subprogram to return to the starting position

Improve and create your own program!